1. Introduction

Time-dependent perturbation theory applies to Hamiltonians of the form

\[ H = H_0 + H_1(t), \]

where \( H_0 \) is solvable and \( H_1 \) is treated as a perturbation. In bound state perturbation theory (see Notes 22) we were interested in the shifts in the energy levels and eigenfunctions of the unperturbed system induced by the perturbation \( H_1 \), which was assumed to be time-independent. In time-dependent perturbation theory, on the other hand, we are usually interested in time-dependent transitions between eigenstates of the unperturbed system induced by the perturbation \( H_1 \). In time-dependent perturbation theory the perturbation \( H_1 \) is allowed to depend on time, as indicated by Eq. (1), but it does not have to be time-dependent, and in fact in practice often it is not. Time-dependent perturbation theory is especially useful in scattering theory, problems involving the emission and absorption of radiation, and in field theoretic problems of various kinds. Such problems will occupy us for the rest of the course.

Time-dependent transitions are usually described by the transition amplitude, defined as the quantity

\[ \langle f | U(t) | i \rangle, \]

where \( U(t) \) is the exact time evolution operator for the Hamiltonian (1), and where \( |i\rangle \) and \( |f\rangle \) are two eigenstates of the unperturbed Hamiltonian \( H_0 \) (the “initial” and “final” states). The transition amplitude can be regarded as simply a matrix element of the exact time evolution operator in the eigenbasis of the unperturbed Hamiltonian, but it is also the amplitude to find the system in state \( |f\rangle \) when it was known to be in the state \( |i\rangle \) at \( t = 0 \). Thus, the absolute square of the transition amplitude is the transition probability, the probability to make the transition \( i \to f \) in time \( t \). Often we are interested in transitions to some collection of final states, in which case we must sum the transition probabilities over all these states.

In these notes we shall develop the basic formalism of time-dependent perturbation theory and study some simple examples. For the most part we shall simply follow the formulas to see where they lead, without examining the conditions of validity or the limitations of the results. We will address those questions in the context of some examples, both in these and in successive notes.
2. Time-Evolution Operators

Let us denote the unperturbed time-evolution operator by $U_0(t)$ and the exact one by $U(t)$. Since the full Hamiltonian may depend on time, the exact time-evolution operator actually depends on two times, $t$ and $t_0$, but we shall set $t_0 = 0$ and just write $U(t)$. See Sec. 5.2. These operators satisfy the evolution equations,

$$i\hbar \frac{\partial U_0(t)}{\partial t} = H_0 U_0(t), \quad (3a)$$

$$i\hbar \frac{\partial U(t)}{\partial t} = H(t) U(t), \quad (3b)$$

which are versions of Eq. (5.13). Since $H_0$ is independent of time, Eq. (3a) can be solved,

$$U_0(t) = e^{-iH_0 t/\hbar}, \quad (4)$$

but if $H_1$ depends on time then there is no similarly simple expression for $U(t)$.

3. The Interaction Picture

The interaction picture is a picture that is particularly convenient for developing time-dependent perturbation theory. It is intermediate between the Schrödinger and Heisenberg pictures that were discussed in Sec. 5.5. Recall that in the Schrödinger picture, the kets evolve in time but the operators do not (at least if they have no explicit time dependence), while in the Heisenberg picture the kets do not evolve but the operators do. In the interaction picture, the time evolution of the kets in the Schrödinger picture that is due to the unperturbed system $H_0$ is stripped off, leaving only the evolution due to the perturbation $H_1$. This is presumably slower than the evolution due to the whole Hamiltonian $H$, since $H_1$ is assumed small compared to $H_0$. We will not attempt to state precisely what “small” means in this context, rather we will develop the perturbation expansion as a power series in $H_1$ and then examine its limitations in various examples.

In the following we shall use an $S$ subscript on kets and operators in the Schrödinger picture, and an $I$ on those in the interaction picture. We will not use the Heisenberg picture in these notes. If the subscript is omitted, the Schrödinger picture will be assumed. The the relation between the kets in the Schrödinger and interaction pictures is

$$|\psi_I(t)\rangle = U_0^\dagger(t)|\psi_S(t)\rangle. \quad (5)$$

Compare this to Eq. (5.17), which shows the relation between kets in the Schrödinger and Heisenberg pictures. The difference is that in Eq. (5) we are only stripping off the evolution due to $H_0$, not the whole time evolution. Notice that at $t = 0$ the Schrödinger and interaction picture kets agree,

$$|\psi_I(0)\rangle = |\psi_S(0)\rangle. \quad (6)$$

As for operators in the interaction picture, they are defined by

$$A_I(t) = U_0^\dagger(t)A_S(t)U_0(t). \quad (7)$$
In practice $A_S$ is often time-independent, but $A_I$ is always time-dependent. Compare this to Eq. (5.19), which shows the relation between operators in the Schrödinger and Heisenberg pictures.

4. Evolution in the Interaction Picture

Let us define $W(t)$ as the operator that evolves kets in the interaction picture forward from time $0$ to final time $t$:

$$|\psi_I(t)\rangle = W(t)|\psi_I(0)\rangle.$$  \hspace{1cm} (8)

The operator $W(t)$ is a time-evolution operator, but we use the symbol $W$ to avoid confusion with the two other time-evolution operators introduced so far, $U_0(t)$ and $U(t)$.

It is easy to find a relation among these three operators. Substituting Eqs. (5) and (6) into Eq. (8), we have

$$|\psi_I(t)\rangle = U_0(t)\dagger |\psi_S(t)\rangle = U_0(t)\dagger U(t)|\psi_S(0)\rangle = W(t)|\psi_I(0)\rangle,$$ \hspace{1cm} (9)

or, since $|\psi_I(0)\rangle$ is arbitrary,

$$W(t) = U_0(t)\dagger U(t).$$ \hspace{1cm} (10)

The operator $W(t)$ is equivalent to first evolving forward for time $t$ under the exact Hamiltonian, then evolving backwards for the same time under the unperturbed Hamiltonian.

5. The $S$-Matrix

For an application in which the interaction picture leads to an interesting perspective, consider a scattering experiment in which a wave packet is directed against a target, described by a potential $U(x)$. We assume that the potential dies off rapidly with distance, and that at the initial time the wave packet is far enough away from the scatterer that it is essentially free. For simplicity we assume that the potential (or other perturbing Hamiltonian) is time-independent.

Initially the wave packet evolves according to the free particle Hamiltonian, since it does not overlap with the potential. That is, the wave packet moves with an average velocity and simultaneously spreads, as studied in Prob. 5.3. After some time, however, the wave packet begins to interact with the potential, producing a scattered wave that radiates outward from the potential in various directions. Depending on the size of the wave packet and that of the scatterer, some of the wave packet may effectively miss the scatterer and proceed in the forward direction, largely unaffected by the scattering process. In any case, after some time the scattered wave and the remaining part of the incident wave packet move away from the scatterer, and once again evolve according to the free particle Hamiltonian. Thus, the exact time evolution is that of a free particle both at large negative times and large positive times.

Let us now view the evolution of the quantum state in the interaction picture. Initially and for large negative times the wave function in the Schrödinger picture evolves according to the free particle Hamiltonian, so in the interaction picture the wave function does not evolve at all. The wave function
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in the interaction picture does not begin to change until the wave packet in the Schrödinger picture starts to interact with the potential. Then the wave packet in the interaction picture does evolve, and continues to do so as long as the Schrödinger wave function has any overlap with the scatterer. As the Schrödinger wave function leaves the region of the scatterer, however, the wave function in the interaction picture ceases to evolve, and at large positive times it approaches another, constant wave function.

Thus, the interaction picture kets $|\psi_I(-T)\rangle$ and $|\psi_I(T)\rangle$ approach constant kets as $T \to \infty$. The scattering process associates a given initial state $\lim_{T \to \infty} |\psi_I(-T)\rangle$ with a definite final state $\lim_{T \to \infty} |\psi_I(T)\rangle$. This association is linear, and defines the S-matrix. It is usually called a “matrix” but really it is an operator, whose matrix elements in some basis form a matrix. The usual basis is that of free particle states, that is, plane waves. In this form, the S-matrix bears a close relationship to the cross section.

We can easily express the S-matrix (or operator) in terms of time-evolution operators. Since

$$|\psi_I(-T)\rangle = W(-T)|\psi_I(0)\rangle \quad \text{and} \quad |\psi_I(T)\rangle = W(T)|\psi_I(0)\rangle,$$

we have

$$|\psi_I(T)\rangle = W(T)W(-T)^\dagger|\psi_I(-T)\rangle.$$  \hspace{1cm} (11)

But

$$W(T)W(-T)^\dagger = U_0^\dagger(T)U(T)[U_0^\dagger(-T)U(-T)]^\dagger = U_0^\dagger(T)U(2T)U_0^\dagger(T),$$  \hspace{1cm} (12)

where we have used $U_0^\dagger(T) = U_0(-T)$ and $U^\dagger(T) = U(-T)$. But by the definition of the S operator, this implies

$$S = \lim_{T \to \infty} U_0^\dagger(T)U(2T)U_0^\dagger(T).$$  \hspace{1cm} (13)

The S-matrix is a central object in advanced treatments of scattering theory, but its mathematics involves noncommuting limits and is tricky. In these notes we take a simpler approach to scattering theory, one that involves a straightforward perturbation expansion of the operator $W(t)$ in powers of the perturbing Hamiltonian $H_1$.

6. The Dyson Series

We obtain a differential equation for $W(t)$ by differentiating Eq. (10) and using Eqs. (3),

$$i\hbar \frac{\partial W(t)}{\partial t} = i\hbar \frac{\partial U_0(t)}{\partial t} U(t) + U_0(t)^\dagger i\hbar \frac{\partial U(t)}{\partial t} = -U_0(t)^\dagger H_0 U(t) + U_0(t)^\dagger H U(t)$$

$$= U_0(t)^\dagger H_1 U(t) = [U_0(t)^\dagger H_1 U_0(t)][U_0(t)^\dagger U(t)],$$  \hspace{1cm} (14)

where we have used $H = H_0 + H_1$ in the third equality, whereupon the terms in $H_0$ cancel. The result can be written,

$$i\hbar \frac{\partial W(t)}{\partial t} = H_1(t)W(t),$$  \hspace{1cm} (15)
an equation of the same form as Eqs. (3), but one in which only the perturbing Hamiltonian $H_1$ appears, and that in the interaction picture. By applying both sides of Eq. (16) to the initial state $|\psi_I(0)\rangle$, we obtain a version of the Schrödinger equation in the interaction picture,

$$i\hbar \frac{\partial |\psi_I(t)\rangle}{\partial t} = H_{1I}(t)|\psi_I(t)\rangle.$$  

(17)

It is now easy to obtain a solution for $W(t)$ as a power series in the perturbing Hamiltonian $H_1$. First we integrate Eq. (16) between time 0 and time $t$, obtaining

$$W(t) = 1 + \frac{1}{i\hbar} \int_0^t dt' H_{1I}(t') W(t'),$$  

(18)

where we have used $W(0) = 1$. This is an exact result, but it is not a solution for $W(t)$, since $W(t)$ appears on the right-hand side. But by substituting the left-hand side of Eq. (18) into the right-hand side, that is, iterating the equation, we obtain

$$W(t) = 1 + \frac{1}{i\hbar} \int_0^t dt' H_{1I}(t') + \frac{1}{(i\hbar)^2} \int_0^t dt' \int_0^{t'} dt'' H_{1I}(t') H_{1I}(t'') W(t''),$$  

(19)

another exact equation in which the term containing $W(t)$ on the right hand side has been pushed to second order. Substituting Eq. (18) into the right-hand side of Eq. (19) pushes the term in $W(t)$ to third order, etc. Continuing in this way, we obtain a formal power series for $W(t)$,

$$W(t) = 1 + \frac{1}{i\hbar} \int_0^t dt' H_{1I}(t') + \frac{1}{(i\hbar)^2} \int_0^t dt' \int_0^{t'} dt'' H_{1I}(t') H_{1I}(t'') + \ldots.$$  

(20)

This series is called the Dyson series. It is obviously a kind of a series expansion of $W(t)$ in powers of $H_1$.

7. The Usual Problem

Let us assume for simplicity that $H_0$ has a discrete spectrum, and let us write

$$H_0 |n\rangle = E_n |n\rangle,$$  

(21)

where $n$ is a discrete index. The usual problem in time-dependent perturbation theory is to assume that the system is initially in an eigenstate of the unperturbed system, what we will call the “initial” state $|i\rangle$ with energy $E_i$,

$$H_0 |i\rangle = E_i |i\rangle.$$  

(22)

This is just a special case of Eq. (21) (with $n = i$). That is, we assume the initial conditions are

$$|\psi_I(0)\rangle = |\psi_S(0)\rangle = |i\rangle.$$  

(23)

We will be interested in finding the state of the system at a later time,

$$|\psi_I(t)\rangle = W(t)|i\rangle.$$  

(24)

By applying the Dyson series (20) to this equation, we obtain a perturbation expansion for $|\psi_I(t)\rangle$,

$$|\psi_I(t)\rangle = |i\rangle + \frac{1}{i\hbar} \int_0^t dt' H_{1I}(t') |i\rangle + \frac{1}{(i\hbar)^2} \int_0^t dt' \int_0^{t'} dt'' H_{1I}(t') H_{1I}(t'') |i\rangle + \ldots.$$  

(25)
8. Transition Amplitudes

Let us expand the exact solution of the Schrödinger equation in the interaction picture in the unperturbed eigenstates,

\[ |\psi_I(t)\rangle = \sum_n c_n(t) |n\rangle, \tag{26} \]

with coefficients \( c_n(t) \) that are functions of time. We can solve for these coefficients by multiplying Eq. (26) on the left by the bra \( \langle n| \), which gives

\[ c_n(t) = \langle n| W(t)|i\rangle, \tag{27} \]

showing that \( c_n(t) \) is a transition amplitude in the interaction picture, that is, a matrix element of the time-evolution operator \( W(t) \) in the interaction picture with respect to the unperturbed eigenbasis. These are not the same as the transition amplitudes (2), which are the matrix elements of \( U(t) \) (the time-evolution operator for kets in the Schrödinger picture) with respect to the unperturbed eigenbasis. There is, however, a simple relation between the two. That is, substituting Eq. (10) into Eq. (27), we have

\[ c_n(t) = \langle n| U_0(t)^\dagger U(t)|i\rangle = e^{iE_n t/\hbar} \langle n| U(t)|i\rangle, \tag{28} \]

where we have allowed \( U_0(t)^\dagger \) to act to the left on bra \( \langle n| \). We see that the transition amplitudes in the interaction picture and those in the Schrödinger picture are related by a simple phase factor. The phase factor removes the rapid time evolution of the transition amplitudes in the Schrödinger picture due to the unperturbed system, leaving behind the slower evolution due to \( H_1 \). The transition probabilities are the squares of the amplitudes and are the same in either case,

\[ P_n(t) = |c_n(t)|^2 = |\langle n| W(t)|i\rangle|^2 = |\langle n| U(t)|i\rangle|^2. \tag{29} \]

The perturbation expansion of the transition amplitude \( c_n(t) \) is easily obtained by multiplying Eq. (25) by the bra \( \langle n| \). We write the result in the form,

\[ c_n(t) = \delta_{ni} + c_n^{(1)}(t) + c_n^{(2)}(t) + \ldots, \tag{30} \]

where the parenthesized numbers indicate the order of perturbation theory, and where

\[ c_n^{(1)}(t) = \frac{1}{i\hbar} \int_0^t dt' \langle n| H_1(t')|i\rangle, \tag{31a} \]

\[ c_n^{(2)}(t) = \frac{1}{(i\hbar)^2} \int_0^t dt' \int_0^{t'} dt'' \langle n| H_1(t') H_1(t'')|i\rangle, \tag{31b} \]

etc.

We now switch back to the Schrödinger picture in the expressions for the \( c_n^{(r)} \). The interaction picture is useful for deriving the perturbation expansion, but the Schrödinger picture is more convenient for subsequent calculations. For \( c_n^{(1)} \), we have

\[ c_n^{(1)}(t) = \frac{1}{i\hbar} \int_0^t dt' \langle n| U_0^\dagger(t') H_1(t') U_0(t') |i\rangle \]

\[ = \frac{1}{i\hbar} \int_0^t dt' e^{i\omega_n t'} \langle n| H_1(t')|i\rangle, \tag{32} \]
where we have allowed $U_0(t')\dagger$ and $U_0(t')$ to act to the left and right, respectively, on bra $\langle n|$ and ket $|i\rangle$, bringing out the phase factor $e^{i\omega_{ni}t'}$ where $\omega_{ni}$ is the Einstein frequency connecting unperturbed states $n$ and $i$,

$$\omega_{ni} = \frac{E_n - E_i}{\hbar}.$$  

(33)

As for $c_n^{(2)}$, it is convenient to introduce a resolution of the identity $\sum |k\rangle\langle k|$ between the two factors of $H_1I$ in Eq. (31b) before switching to the Schrödinger picture. This gives

$$c_n^{(2)}(t) = \frac{1}{(\hbar)^2} \int_0^t dt' \int_0^{t'} dt'' \sum_k e^{i\omega_{nk}t' + i\omega_{ki}t''} \langle n|H_1(t')|k\rangle \langle k|H_1(t'')|i\rangle.$$  

(34)

From this the pattern at any order of perturbation theory should be clear. In Eq. (34), the states $|k\rangle$ are known as intermediate states, the idea being that there is a time sequence as we move from the right to the left in the product of matrix elements, starting with the initial state $|i\rangle$, moving through the intermediate state $|k\rangle$ and ending with the final state $|n\rangle$. Notice that the variables of integration satisfy $0 \leq t'' \leq t' \leq t$.

9. The Case that $H_1$ is Time-independent

This is about as far as we can go without making further assumptions about $H_1$, so that we can do the time integrals. Let us now assume that $H_1$ is time-independent, an important case in practice. Then the matrix elements are independent of time and can be taken out of the integrals, and the integrals that remain are elementary. For example, in Eq. (32) we have the integral

$$\int_0^t dt' e^{i\omega t'} = 2e^{i\omega t/2} \frac{\sin \omega t/2}{\omega},$$  

(35)

so that

$$c_n^{(1)}(t) = \frac{2}{i\hbar} e^{i\omega_{ni}t/2} \left(\frac{\sin \omega_{ni}t/2}{\omega_{ni}}\right) \langle n|H_1|i\rangle.$$  

(36)

The case of $c_n^{(2)}$ is similar but more complicated. We will return to it later when we have an application of second order time-dependent perturbation theory.

The transition probability $P_n(t)$ can also be expanded in the perturbation series,

$$P_n(t) = |c_n(t)|^2 = |\delta_{ni} + c_n^{(1)}(t) + c_n^{(2)}(t) + \ldots|^2.$$  

(37)

Notice that on taking the square there are cross terms, that is, interference terms between the amplitudes at different orders.

For now we assume that the final state we are interested in is not the the initial state, that is, we take the case $n \neq i$ so the first term in Eq. (37) vanishes, and we work only to first order of perturbation theory. Then we have

$$P_n(t) = |c_n^{(1)}(t)|^2 = \frac{4}{\hbar^2} \left(\frac{\sin^2 \omega_{ni}t/2}{\omega_{ni}^2}\right) |\langle n|H_1|i\rangle|^2.$$  

(38)
The transition probability depends on time and on the final state \( n \). As for the time dependence, it is contained in the first factor in the parentheses, while both this factor and the matrix element depend on the final state \( |n\rangle \). However, the factor in the parentheses depends on the state \( n \) only through its energy \( E_n \), which is contained in the Einstein frequency \( \omega_{ni} \), while the matrix element depends on all the properties of the state \( |n\rangle \), for example, its momentum, spin, etc.

10. The Case of Time-Periodic Perturbations

Another case that is important in practice is when \( H_1 \) has a periodic time dependence of the form

\[
H_1(t) = Ke^{-i\omega_0 t} + K^\dagger e^{i\omega_0 t},
\]

where \( \omega_0 \) is the frequency of the perturbation and \( K \) is an operator (generally not Hermitian). We call the first and second terms in this expression the positive and negative frequency components of the perturbation, respectively. This case applies, for example, to the interaction of spins or atoms with a given, classical electromagnetic wave.

To find the transition amplitude in this case we substitute Eq. (39) into Eq. (32) and perform the integration, whereupon we obtain two terms,

\[
\langle n|K|i\rangle = 2\hbar \left[ e^{i(\omega_{ni} - \omega_0)t/2} \frac{\sin(\omega_{ni} - \omega_0)t/2}{\omega_{ni} - \omega_0} \langle n|K|i\rangle + e^{i(\omega_{ni} + \omega_0)t/2} \frac{\sin(\omega_{ni} + \omega_0)t/2}{\omega_{ni} + \omega_0} \langle n|K^\dagger|i\rangle \right].
\]

(40)

For any given final state \( n \), both these terms are present and contribute to the transition amplitude. And when we square the amplitude to get the transition probability, there are cross terms (interference terms) between these two contributions to the amplitude.

Often, however, we are most interested in those final states to which most of the probability goes, which are the states for which one or the other of the two denominators in Eq. (40) is small. For these states we have \( \omega_{ni} \mp \omega_0 \approx 0 \), or

\[
E_n \approx E_i \pm \hbar \omega_0.
\]

(41)

We see that the first (positive frequency) term is resonant when the system has absorbed a quantum of energy \( \hbar \omega_0 \) from the perturbation, whereas the second (negative frequency) term is resonant when the system has given up a quantum of energy \( \hbar \omega_0 \) to the perturbation. We call these two cases absorption and stimulated emission, respectively.

Taking the case of absorption, and looking only at final states \( |n\rangle \) that are near resonance \( (E_n \approx E_i + \hbar \omega_0) \), we can write the transition probability to first order of perturbation theory as

\[
P_n = \frac{4}{\hbar^2} \left[ \frac{\sin^2(\omega_{ni} - \omega_0)t/2}{(\omega_{ni} - \omega_0)^2} \right] |\langle n|K|i\rangle|^2.
\]

(42)
Similarly, for nearly resonant final states in stimulated emission, we have

\[ P_n = \frac{4}{\hbar^2} \left[ \frac{\sin^2 (\omega_{ni} + \omega_0) t/2}{(\omega_{ni} + \omega_0)^2} \right] |\langle n|K^\dagger|i \rangle|^2. \]  

(43)

These formulas may be compared to Eq. (38). In all cases, \( P_n \) has a dependence on time that is described by functions of a similar form.

11. How \( P_n \) Depends on Time

Let us fix the final state \( |n\rangle \) and examine how the probability \( P_n(t) \) develops as a function of time in first order time-dependent perturbation theory. To be specific we will take the case of a time-independent perturbation and work with Eq. (38), but with \( \omega_{ni} \) replaced by \( \omega_{ni} \pm \omega_0 \) and \( H_1 \) replaced by \( K \) or \( K^\dagger \), everything we say also applies to absorption or stimulated emission.

Obviously \( P_n(0) = 0 \) (because \( n \neq i \) and all the probability lies in state \( |i\rangle \) at \( t = 0 \)). At later times we see that \( P_n(t) \) oscillates at frequency \( \omega_{ni} \) between 0 and a maximum proportional to \( 1/\omega_{ni}^2 \). The frequency \( \omega_{ni} \) measures how far the final state is “off resonance,” that is, how much the final energy differs from the initial energy. In some applications this difference can be regarded as a failure to conserve energy, which is allowed over finite time intervals by the energy-time uncertainty relation \( \Delta E \Delta t \approx \hbar \). If \( \omega_{ni} \) is large, the probability \( P_n(t) \) oscillates rapidly between zero and a small maximum. But as we move the state \( |n\rangle \) closer to the initial state \( |i\rangle \) in energy, \( \omega_{ni} \) gets smaller, the period of oscillations becomes longer, and the amplitude grows.

If there is a final state \( |n\rangle \) degenerate in energy with the initial state \( |i\rangle \) (not the same state since we are assuming \( n \neq i \)), then \( \omega_{ni} = 0 \) and the time-dependent factor in Eq. (38) takes on its limiting value, which is \( t^2/4 \). In this case, first order perturbation theory predicts that the probability \( P_n(t) \) grows without bound, obviously an absurdity after a while since we must have \( P_n \leq 1 \). This is an indication of the fact that at sufficiently long times first order perturbation theory breaks down and we must take into account higher order terms in the perturbation expansion. In fact, to get sensible results at such long times, it is necessary to take into account an infinite number of terms (that is, to do some kind of summation of the series). But at short times it is correct that \( P_n \) for a state on resonance grows as \( t^2 \).

These considerations are important when the system has a discrete spectrum, for example, when a spin is interacting with a time-periodic magnetic field or when we are looking at a few discrete states of an atom in the presence of laser light. These are important problems in practice. Recall that in Notes 14 we solved the Schrödinger equation exactly for a spin in a certain kind of time-periodic magnetic field, but in more general cases an exact solution is impossible and we may have to use time-dependent perturbation theory. It is interesting to compare the exact solution presented in Notes 14 with the perturbative solutions presented here, to see the limitations of the perturbative solutions.

In such problems with a discrete spectrum, the resonance condition \( \omega_{ni} = 0 \) may not be satisfied exactly for any final state \( n \neq i \). In fact, in problems of emission and absorption, if the frequency
\( \omega_0 \) of the perturbation is chosen randomly, then it is unlikely that the resonant energy \( E_i \pm \hbar \omega_0 \) will exactly coincide with any unperturbed energy eigenvalue. In that case, first-order theory predicts that the transition probability to all final states just oscillates in time.

On the other hand, if the final states are members of a continuum, then there are an infinite number of final states arbitrarily close to the initial state in energy. For those cases, we must examine how the transition probability depends on energy.

12. How \( P_n \) Depends on Energy

Now let us fix the time \( t \) and examine how the expression for \( P_n(t) \) in first order perturbation theory, Eq. (38), depends on the energy \( E_n \) of the final state \( |n\rangle \) (working for simplicity with the case of a time-independent perturbation). We shall concentrate on the energy dependence of the time-dependent factor in the parentheses, remembering that the matrix element also depends on the energy (and other parameters) of the final state. To do this we plot the function \( \sin^2(\omega t/2)/\omega^2 \) as a function of \( \omega \), as shown in Figs. 1 and 2 for two different times. In the plot, \( \omega \) is to be identified with \( \omega_{ni} = (E_n - E_i)/\hbar \), so that \( \omega \) specifies the energy of the final state and \( \omega = 0 \) is the resonance (energy conserving) condition.

The curve consists of oscillations under the envelope \( 1/\omega^2 \), with zeroes at \( \omega = (2n\pi/t) \). The central lobe has height \( t^2/4 \) and width that is proportional to \( 1/t \), so the area of the central lobe is proportional to \( t \). As \( t \) increases, the central lobe grows in height and gets narrower, a behavior that reminds us of functions that approach a \( \delta \)-function, but in this case the limit is not a \( \delta \)-function because the area is not constant. In fact, the total area is given exactly by an integral that can be
evaluated by contour integration,
\[ \int_{-\infty}^{+\infty} d\omega \frac{\sin^2 \omega t/2}{\omega^2} = \frac{\pi t}{2}, \]  
showing that the area is indeed proportional to \( t \). Thus if we divide by \( t \) we do get a \( \delta \)-function as \( t \rightarrow \infty \),
\[ \lim_{t \rightarrow \infty} \frac{1}{t} \frac{\sin^2 \omega t/2}{\omega^2} = \frac{\pi}{2} \delta(\omega). \]  
For fixed \( \omega \neq 0 \) the function under the limit in this expression approaches 0 as \( t \rightarrow \infty \), while exactly at \( \omega = 0 \) it grows in proportion to \( t \), with a constant total area. This is exactly the behavior that produces a \( \delta \)-function in the limit.

In physical applications we never really go to infinite time, rather we work with times long enough that there is negligible error in replacing the function on the left-hand side of Eq. (45) by its limit. To deal with the case of finite time, we introduce the notation,
\[ \frac{\sin^2 \omega t/2}{\omega^2} = \frac{\pi}{2} t \Delta_t(\omega), \]  
which defines the function \( \Delta_t(\omega) \). Then the limit (45) can be written,
\[ \lim_{t \rightarrow \infty} \Delta_t(\omega) = \delta(\omega). \]  

As we shall see when we take up some applications, the \( \delta \)-function in Eq. (45) enforces energy conservation in the limit \( t \rightarrow \infty \), that is, only transitions to final states of the same energy as the initial state are allowed in that limit. At finite times, transitions take place to states in a range of energies about the initial energy, given in frequency units by the width of the function \( \Delta_t(\omega) \). But as we have seen this width is of order \( 1/t \), or, in energy units, \( \hbar/t \). This is an example of the energy-time uncertainty relation, \( \Delta E \Delta t > \approx \hbar \), indicating that a system that is isolated over a time interval \( \Delta t \) has an energy that is uncertain by an amount \( \Delta E > \approx \hbar/\Delta t \).

Now we can write the transition probability (38) as
\[ P_n(t) = \frac{2\pi t}{\hbar^2} \Delta_t(\omega_{ni}) \left| \langle n|H_1|i \rangle \right|^2. \]  
This applies in first order perturbation theory, in the case \( n \neq i \).

The case \( n = i \) is also of interest, and can be analyzed similarly. We will return to this case later in the course.

13. Cross Sections and Differential Cross Sections

In preparation for applications to scattering, we make a digression to define and discuss cross sections and differential cross sections. These concepts are best understood in a classical context, but most of the ideas carry over without trouble into quantum mechanics.
We first discuss classical scattering from a fixed target, which is illustrated in Fig. 3. An incident beam of particles of momentum $p$ and uniform density is directed against a target, illustrated by the shaded region in the figure. The target is described by a potential $U(x)$. The origin of a coordinate system is located in or near the target, and in the figure the beam is directed in the $z$-direction. A transverse plane $T$ is erected perpendicular to the beam at a large, negative value of $z$, where the potential $U(x)$ is negligible. The plane $T$ is parallel to the $x$-$y$ plane, and when the particles cross it their momentum is purely in the $z$-direction, since no interaction with the potential has occurred yet. The negative $z$-axis is extended back to the plane $T$ along a center line $C$, intersecting it at point $O$, which serves as an origin in the plane.

The trajectory of one particle is illustrated in the figure. It crosses the plane $T$ at a position described by the impact parameter, a vector $b$, which goes from the origin $O$ in the plane to the intersection point. The impact parameter only has $x$- and $y$-components. The particle continues forward and interacts with the potential, going out in some direction $\hat{n} = (\theta, \phi)$. This direction is defined asymptotically, that is, it is the direction of the particle’s momentum when it is once again at a large distance from the target. The outgoing direction is a function of the impact parameter,

$$\hat{n} = \hat{n}(b),$$  \hspace{1cm} (49)

which can be determined by integrating the equations of motion from given initial conditions on the plane $T$.

Now let us construct a small cone of solid angle $\Delta\Omega$, centered on the outgoing direction $\hat{n} = (\theta, \phi)$, as illustrated in Fig. 4. The particles whose asymptotic, outgoing directions lie inside this cone cross the plane $T$ inside an area indicated by the shaded area in plane $T$ in the figure. This area represents the portion of the incident flux of particles that is directed into the small cone by the scattering process. It defines the differential cross section $d\sigma/d\Omega$ by the formula,

$$\text{Area} = \frac{d\sigma}{d\Omega} \Delta\Omega.$$  \hspace{1cm} (50)

The differential cross section $d\sigma/d\Omega$ is a function of $(\theta, \phi)$. 

Fig. 3. Classical scattering of particles. The outgoing asymptotic direction $\hat{n} = (\theta, \phi)$ is a function of the impact parameter $b$. 

Fig. 4. Illustration of a small cone of solid angle $\Delta\Omega$, centered on the outgoing direction $\hat{n} = (\theta, \phi)$. The particles whose asymptotic, outgoing directions lie inside this cone cross the plane $T$ inside an area indicated by the shaded area in plane $T$.
Another point of view deals with counting rates. We use the symbol \( w \) to stand for a rate, with dimensions of time\(^{-1} \), for example, number of particles per unit time or probability per unit time. A detector situated in Fig. 4 so as to intercept all particles coming out in the cone will have a counting rate given by the rate at which particles cross the shaded area in plane \( T \). We denote this counting rate by \( (dw/d\Omega)\Delta\Omega \). But this is just the flux of incident particles times the shaded area, that is,

\[
\frac{dw}{d\Omega} = J_{\text{inc}} \frac{d\sigma}{d\Omega}.
\]

As for the incident flux, it is given by

\[
J_{\text{inc}} = n v,
\]

where \( n \) is the number of particles per unit volume in the incident beam and \( v = p/m \) is the incident velocity. The magnitude \( J_{\text{inc}} = |J_{\text{inc}}| \) appears in Eq. (51), since the transverse plane is orthogonal to the velocity \( v \). It is obvious that the counting rate is proportional to the incident flux, so Eq. (51) gives another way of thinking about the differential cross section: It is the counting rate, normalized by the incident flux.

The total scattering rate \( w \) is the rate at which particles are scattered at any nonzero angle. It is the integral of the differential scattering rate,

\[
w = \int d\Omega \frac{dw}{d\Omega}.
\]

It is related to the total cross section \( \sigma \) by

\[
w = J_{\text{inc}} \sigma,
\]

where

\[
\sigma = \int d\Omega \frac{d\sigma}{d\Omega}.
\]

In classical scattering, the total cross section is often infinite, due to a large number of particles that are scattered by only a small angle.
The relation (51) applies in the case of a single scatterer located inside the incident beam. In many practical circumstances there are multiple, identical scatterers. An example is Rutherford’s original scattering experiment, in which a beam of $\alpha$-particles is directed against a gold foil. The individual gold nuclei are the scatterers, of which there are a large number in the region of the foil crossed by the beam.

In this case we can speak of the scattering rate (differential or total) per unit volume of the scattering material, which is $n_{\text{inc}}n_{\text{targ}}v$ times the cross section (differential or total), where $n_{\text{inc}}$ and $n_{\text{targ}}$ are the number of incident particles and scatterers per unit volume, respectively. Then integrating over the interaction region, we find that Eq. (51) is replaced by

$$\frac{dw}{d\Omega} = \frac{d\sigma}{d\Omega} v \int d^3 x \, n_{\text{inc}} n_{\text{targ}},$$

(56)

where $v$ is again the velocity of the beam. In this formula, both $n_{\text{inc}}$ and $n_{\text{targ}}$ can be functions of position, as they often are in practice. We are assuming that $v$ is constant, so that it can be taken out of the integral (the beam consists of particles of a given momentum).

Another case that is common in practice is when there are two beams intersecting one another. In this case it is easiest to work in the center-of-mass frame, in which the momenta of the particles in the two beams are equal and opposite. As we have seen in Notes 16, when two particles interact by means of a central force potential, their relative motion is described by a pseudo-one-body problem. Thus, the results for scattering from a fixed target with central force potential $U$ can be transcribed into those for scattering of two particles in the center of mass frame, in which the position vector $\mathbf{x}$ of the beam particle relative to the scatterer is replaced by $\mathbf{r} = \mathbf{x}_2 - \mathbf{x}_1$, the relative position vector between two particles in the two beams, and where the mass $m$ of the beam particle is replaced by the reduced mass $\mu$ of the two particle system. Then the transition rate is given by a modified version of Eq. (56),

$$\frac{dw}{d\Omega} = \frac{d\sigma}{d\Omega} v \int d^3 x \, n_1 n_2,$$

(57)

where $n_1$ and $n_2$ are the densities of the two beams, which may be functions of position, and where $v$ is now the relative velocity of the two beams. The integral is taken over the region where the two beams overlap.

The transformation between the lab positions and momenta of the two particles, $(\mathbf{x}_1, \mathbf{p}_1)$ and $(\mathbf{x}_2, \mathbf{p}_2)$, and the center of mass position and momentum $(\mathbf{R}, \mathbf{P})$ and the relative position and momentum $(\mathbf{r}, \mathbf{p})$, is given by Eqs. (16.44–16.45) and (16.50–16.53). The definitions of $\mathbf{R}$, the center of mass position, and $\mathbf{P} = \mathbf{p}_1 + \mathbf{p}_2$, the total momentum of the two particle system as seen in the lab frame, are clear physically. So also is the definition of $\mathbf{r} = \mathbf{x}_2 - \mathbf{x}_1$, the relative separation between the two particles. But the definition of $\mathbf{p}$, the momentum conjugate to $\mathbf{r}$,

$$\mathbf{p} = \frac{m_1 \mathbf{p}_2 - m_2 \mathbf{p}_1}{m_1 + m_2},$$

(58)

requires some comment. (This is essentially Eq. (16.53)).
We offer two interpretations of this equation. First, we compute $p/\mu$, where $\mu$ is the reduced mass, given by Eq. (16.58), or, equivalently,

$$\mu = \frac{m_1 m_2}{m_1 + m_2}. \tag{59}$$

Dividing this into Eq. (58) gives

$$\frac{p}{\mu} = \frac{p_2}{m_2} - \frac{p_1}{m_1}, \tag{60}$$

or,

$$p = \mu v, \tag{61}$$

where

$$v = v_2 - v_1 \tag{62}$$

is the relative velocity. In other words, we have a version of the usual formula $p = mv$, where $p$ is the momentum conjugate to the relative position vector, $v$ is the relative velocity, and $m$ is replaced by the reduced mass.

Another interpretation is to imagine the two particle system as seen in the center-of-mass frame, in which $P = 0$. If we let $p_2 = q$, then $p_1 = -q$, which when substituted into Eq. (58) gives $p = q$. Thus, the momentum $p$, defined as the conjugate to the relative position $r$, or, equivalently, by Eq. (58), is the momentum of one or the other of the particles (to within a sign) as seen in the center-of-mass frame.


We return now to time-dependent perturbation theory, and examine an application, namely, potential scattering of a spinless particle from a fixed target, described by a potential $U(x)$. We let the unperturbed Hamiltonian be $H_0 = p^2/2m$ and we take the perturbation to be $H_1 = U(x)$, where $U$ is some potential. We do not assume the potential is rotationally invariant, but it should be localized in an appropriate sense. We will examine more carefully the degree of localization required later in the course, when we will also examine other conditions of validity of the theory.

The unperturbed eigenstates are free particle solutions, which we take to be plane waves. In order to deal with discrete final states, we place our system in a large box of side $L$ and volume $V = L^3$, and we adopt periodic boundary conditions. This is equivalent to dividing the universe up into boxes and demanding that all the physics be periodic, that is, the same in all the boxes. We shall assume that the size of the box is much larger than the range of the potential $U(x)$. When we are done we take $V \to \infty$ to get physical results. We denote the unperturbed eigenstates by $|k\rangle$, with wave functions

$$\psi_k(x) = \langle x|k \rangle = \frac{e^{ik \cdot x}}{\sqrt{V}}, \tag{63}$$

so that

$$\langle k|k' \rangle = \delta_{k,k'}. \tag{64}$$
Here we are normalizing the eigenfunctions to the volume of the box, and integrating over the volume of the box when forming scalar products as in Eq. (64). The quantized values of $k$ are given by

$$k = \frac{2\pi}{L}n,$$

(65)

where $n = (n_x, n_y, n_z)$ is a vector of integers, each of which ranges from $-\infty$ to $+\infty$. The unperturbed eigenstates can be represented as a lattice of points in $k$-space, in which the lattice spacing is $2\pi/L$ and the density is $(L/2\pi)^3 = V/(2\pi)^3$. We let $|k_i\rangle$ be an incident plane wave (the initial state), and $|k\rangle$ be some final state.

Notice that the initial state is somewhat unrealistic from a physical standpoint. The initial state is a plane wave $\exp(ik_i \cdot x)$ that fills up all of space, including the region where $U(x)$ is appreciably nonzero. Let us suppose it is a potential well. Thinking in classical terms, it is as if all of space is filled with particles with exactly the same momentum and energy, even the particles in the middle of the well. Of course a particle coming in from infinity and entering a potential well will gain kinetic energy, and the direction of its momentum will change (this is the scattering process in action). But the particles of our initial state in the middle of the potential have the same kinetic energy and momentum as the particles that are coming in from infinity. Obviously this initial condition would be difficult to establish in practice. Nevertheless, it turns out that these particles with the wrong energy and momentum in the initial state do not affect the transition probabilities after sufficiently long times, and so they do not affect the cross section that we shall compute. All they do is give rise to short-time transients that can be regarded as nonphysical since they arise from the artificialities of the initial conditions. We shall say more about these transients below, but for now we shall just continue to follow the formulas of time-dependent perturbation theory.

In this application the perturbing Hamiltonian is time-independent, so the transition amplitude in first order perturbation theory is given by Eq. (36), with the change of notation $|i\rangle \rightarrow |k_i\rangle$, $|n\rangle \rightarrow |k\rangle$, etc. The transition amplitude is

$$\xi_k^{(1)}(t) = \frac{2}{i\hbar} e^{i\omega t/2} \left( \frac{\sin \omega t/2}{\omega} \right) \langle k|U(x)|k_i\rangle,$$

(66)

where

$$\omega = \frac{E_k - E_{k_i}}{\hbar} = \frac{\hbar}{2m}(k^2 - k_i^2),$$

(67)

and the transition probability is

$$\sum_k \frac{2\pi}{\hbar^2} t \Delta_\omega(\omega) |\langle k|U(x)|k_i\rangle|^2,$$

(68)

where we sum over some set of final states for which $k \neq k_i$.

Which final states $k$ do we sum over? This depends on what question we wish to ask. If we are interested in the transition rate to any final state, then we sum over all of them (every lattice point in $k$-space except $k_i$). Often, however, we are interested in more refined information. In the present case, let us sum over all final states (lattice points) that lie in a cone of small solid angle $\Delta\Omega \ll 1$
To compute the differential transition rate $dw/d\Omega$, we sum over all lattice points in $k$-space lying in a small cone of solid angle $\Delta\Omega$ centered on some final vector $k_f$ of interest. The direction $\hat{n}_f$ of $k_f$ determines the $(\theta, \phi)$ dependence of the differential cross section.

In $k$-space, as illustrated in Fig. 5. Let the cone be centered on a direction $\hat{n}_f$, a given unit vector pointing toward some counting device in a scattering experiment. Then define a “final wave vector” $k_f$ by requiring that $k_f$ have the same direction as $\hat{n}_f$, and that it satisfy conservation of energy,

$$\frac{\hbar^2 k_f^2}{2m} = \frac{\hbar^2 k_i^2}{2m},$$

(69)

that is, $k_f = k_i$. Then

$$k_f = k_i \hat{n}_f.$$  

(70)

This is only a definition, and although $k_f$ satisfies energy conservation, notice that the states in the cone that we sum over include states of all energies, from 0 to $\infty$.

With this understanding of the states we sum over in the expression (68), we see that we are computing the probability as a function of time that the system will occupy a momentum state lying in the cone. Under some circumstances transition probabilities are proportional to time, and then we can refer to a transition rate as the probability per unit time for the process in question. We will generally use the symbol $w$ for transition rates. In the present case, we divide the probability (68) by $t$ and write

$$\frac{dw}{d\Omega} \Delta\Omega = \sum_{k \in \text{cone}} \frac{2\pi}{\hbar^2} \Delta_t(\omega) |\langle k | U(x) | k_i \rangle|^2,$$

(71)

where $dw/d\Omega$ is the transition rate per unit solid angle, a quantity that is generally a function of direction, in this case, the direction $\hat{n}_f$.

Notice that the factors of $t$ have cancelled in Eq. (71), but the right-hand side still depends on $t$ through $\Delta_t(\omega)$. If, however, $t$ is large enough that $\Delta_t(\omega)$ can be replaced by $\delta(\omega)$, then the right hand side does become independent of $t$, and the transition rate is meaningful. We see that at short times we do not have a transition rate, but that at longer times we do.
For now let us assume that $t$ is large enough that $\Delta_t(\omega)$ can be replaced by $\delta(\omega)$, since this gives the simplest answer. Later we will examine quantitatively how long we must wait for this to be true. Using Eq. (67), we can transform $\delta(\omega)$ by the rules for $\delta$-functions,

$$\delta(\omega) = \frac{m}{\hbar k_i} \delta(k - k_i). \quad (72)$$

We must also take the limit $V \to \infty$ to obtain physical results. In this limit, the initial wave function $\psi_k(x)$ loses meaning (it goes to zero everywhere, since it is normalized to unity over the volume of the box), as does the differential transition rate $dw/d\Omega$. However, the differential cross section $d\sigma/d\Omega$, which is the differential transition rate normalized by the incident flux, is well defined in the limit. The incident flux is

$$J_{\text{inc}} = n_i v_i = \frac{1}{V} \frac{\hbar k_i}{m}, \quad (73)$$

where $n_i = 1/V$ is the number of particles per unit volume in the incident state, and $v_i = \hbar k_i/m$ is the incident velocity. Thus

$$\frac{d\sigma}{d\Omega} = \frac{V m}{\hbar k_i} \frac{dw}{d\Omega}. \quad (74)$$

Also, in the limit $V \to \infty$, the sum over lattice points $k$ in Eq. (71) can be replaced by an integral,

$$\sum_{k \in \text{cone}} \to \frac{V}{(2\pi)^3} \int_{\text{cone}} d^3 k = \frac{V}{(2\pi)^3} \Delta \Omega \int_0^\infty k^2 dk, \quad (75)$$

where $V/(2\pi)^3$ is the density of states per unit volume in $k$-space and where we have switched to spherical coordinates in $k$-space and done the angular integral over the narrow cone.

Finally we evaluate the matrix element in Eq. (71). It is

$$\langle k | U(x) | k_i \rangle = \int d^3 x \psi_k^* (x) U(x) \psi_{k_i} (x) = \frac{1}{V} \int d^3 x e^{-i(k - k_i) \cdot x} U(x) = \frac{(2\pi)^3/2}{V} \hat{U}(k - k_i), \quad (76)$$

where we use Eq. (63) and define the Fourier transform $\hat{U}(q)$ of the potential $U(x)$ by

$$\hat{U}(q) = \int \frac{d^3 x}{(2\pi)^3} e^{-iq \cdot x} U(x). \quad (77)$$

Putting all the pieces together, we have

$$\frac{d\sigma}{d\Omega} = \frac{V m}{\hbar k_i} \frac{1}{\Delta \Omega (2\pi)^3} \Delta \Omega \int_0^\infty k^2 dk \frac{2\pi m}{\hbar^2 k_i} \delta(k - k_i) \frac{(2\pi)^3}{V^2} |\hat{U}(k - k_i)|^2$$

$$= \frac{2\pi}{\hbar^2} \left( \frac{m}{\hbar k_i} \right)^2 \int_0^\infty k^2 dk \delta(k - k_i) |\hat{U}(k - k_i)|^2, \quad (78)$$

where the factors of $V$ and $\Delta \Omega$ have cancelled, as they must. Notice that $k$ under the integral is a vector, but only its magnitude $k$ is a variable of integration. The direction of $k$ is that of the small cone, that is, $k = k \hat{n}_f$. Now the $\delta$-function makes the integral easy to do. In particular, $k = k \hat{n}_f$ becomes $k_i \hat{n}_f = k_f \hat{n}_f = \hat{k}_f$. Notice that if $t$ is large enough to make the replacement $\Delta_t(\omega) \to \delta(\omega)$
but not infinite, the function $\delta(k - k_i)$ should be understood as a function of small but nonzero width. Thus after finite time $t$ the transitions are actually taking place to states that lie in a small energy range about the initial energy. This is an important point: in time-dependent perturbation theory, we do not attempt to enforce energy conservation artificially, rather our job is to solve the Schrödinger equation, and when we do we find that energy conservation emerges in the limit $t \to \infty$.

The final answer is now easy. It is

$$\frac{d\sigma}{d\Omega} = 2\pi \frac{m^2}{\hbar^4} |\tilde{U}(\mathbf{k}_f - \mathbf{k}_i)|^2. \quad (79)$$

Notice that the momentum transfer in the scattering process is

$$p_f - p_i = \hbar(k_f - k_i), \quad (80)$$

and the differential cross section is a function of this momentum transfer. This result from first-order time-dependent perturbation theory is the same as that obtained in the first Born approximation, to be considered later in the course. As we shall see, the result (79) is valid in the high-energy limit, in which the exact wave function in the midst of the potential does not differ much from the unperturbed wave function.

15. Short-Time Behavior

Let us now estimate the time after which the replacement $\Delta_t(\omega) \to \delta(\omega)$ becomes valid. Let us call this time $t_1$, which we shall estimate as an order of magnitude.

The function $\Delta_t(\omega)$ has a width in $\omega$ given by $\Delta \omega = 1/t$, as an order of magnitude, or, in energy units, $\Delta E = \hbar/t$. We can convert this to wavenumber units by using

$$\Delta E = \frac{\hbar^2 k \Delta k}{m}, \quad (81)$$

or,

$$\Delta k = \frac{m}{\hbar k t}. \quad (82)$$

This is the width of the function we are writing as $\delta(k - k_i)$ under the integral in Eq. (78). The replacement of this function by an exact delta function is valid if this $\Delta k$ is much less than the scale of variation of the function $\tilde{U}(\mathbf{k}\hat{n}_f - \mathbf{k}_i)$ with respect to $k$, that is, the increment in $k$ over which $\tilde{U}$ undergoes a significant change. To estimate this, let us suppose that the potential $U(x)$ has a range (in real space) of $a$, that is, it falls to zero rapidly outside this radius. Then the Fourier transform $\tilde{U}$ will have a width of order $1/a$ with respect to $k$. Thus, the condition under which $\Delta_t(\omega)$ can be replaced by $\delta(\omega)$ is

$$\frac{m}{\hbar k t} \ll \frac{1}{a}, \quad (83)$$

or,

$$t \gg t_1 = \frac{am}{\hbar k} = \frac{a}{v}. \quad (84)$$
where \( v \) is the velocity of the particles in the incident beam. But this is of the order of the time it takes for one of these particles to traverse the range of the potential, that is, it is approximately the time over which the scattering takes place.

It is also the time required for the “unphysical” particles in the initial state, the ones that find themselves in the midst of the potential at \( t = 0 \) with the wrong energy and momentum, to get scattered out of the potential and to be replaced by new particles that come in from the incident beam. As these particles are scattered also, there develops a “front” of scattered particles, moving away from the scatterer, while a steady state develops behind the front. As time goes on, the unphysical particles become proportionally unimportant in the accounting of the transition rate. Thus the transients at times \( t < t_1 \) in the solution of the Schrödinger equation are related to the artificiality of the initial conditions.

This line of physical reasoning is essentially classical, but it suggests that at a fixed distance from the scatterer, the exact time-dependent solution of the Schrödinger equation, the wave function \( \psi_S(x, t) = \langle x | U(t) | k_i \rangle \) in the Schrödinger picture, actually approaches a quantum stationary state, that is, an energy eigenfunction of the full Hamiltonian \( H_0 + H_1 \), in the limit \( t \to \infty \). This eigenfunction has the time dependence \( e^{-iE_i \hbar t / \hbar} \), that is, it has the same energy as the free particle state \( | k_i \rangle \). One must simply wait for the front and any dispersive tail trailing behind it to pass, and then one has a steady stream of outgoing particles. To be careful about this argument, one must worry about bound states of the potential, which correspond to the unphysical particles in the classical picture whose energy is too low to escape from the potential well. We will not pursue this line of reasoning further, but it is an example of how the time-dependent and time-independent points of view are related to one another and how they permeate scattering theory.

Later we will see other examples of short-time transients in other applications of time-dependent perturbation theory, and they always represent nonphysical effects having to do with the artificiality of the initial conditions. We can ignore them if all we want are physical answers.

16. Two-Body Central Force Scattering

A variation on the analysis of Sec. 14 is two-body scattering from a central force potential. The two-body Hamiltonian is

\[
H = \frac{p_1^2}{2m_1} + \frac{p_2^2}{2m_2} + U(|x_2 - x_1|) = \frac{P^2}{2M} + \frac{p^2}{2\mu} + U(r) = H_{CM} + H_{rel},
\]

(85)

where we have transformed the lab coordinates and momenta to center-of-mass and relative coordinates and momenta, as in Notes 16. Here \( M = m_1 + m_2 \) is the total mass and \( \mu \), given by Eq. (59) or (16.58), is the reduced mass. Also, the center-of-mass and relative Hamiltonians are

\[
H_{CM} = \frac{P^2}{2M}, \quad H_{rel} = \frac{p^2}{2\mu} + U(r).
\]

(86)

To compute the cross section it is easiest to work with \( H_{rel} \) and to ignore \( H_{CM} \). Then we have an effective one-body problem that can be analyzed by the same method as in Sec. 14, with \( x \) replaced
by \( \mathbf{r} \) and \( m \) replaced by \( \mu \). Also, \( \mathbf{p} \) is now interpreted as the momentum conjugate to \( \mathbf{r} \), which was discussed in Sec. 13.

We take \( H_0 = p^2/2\mu \) and \( H_1 = U(r) \). The unperturbed eigenstates are plane waves \(|\mathbf{k}\rangle\) of momentum \( \mathbf{p} = \hbar \mathbf{k} \), as in Sec. 14, normalized to a box of volume \( V \),

\[
\psi_k(\mathbf{r}) = \langle \mathbf{k}|\mathbf{r}\rangle = \frac{e^{i\mathbf{k}\cdot\mathbf{r}}}{\sqrt{V}},
\]

exactly as in Eq. (63). Physically, \( \mathbf{k} \) can be interpreted as \( \mathbf{k}^2 = -\mathbf{k}_1 \) when the lab frame is identified with the center-of-mass frame, as discussed in Sec. 13.

We compute the probability of making a transition \(|\mathbf{k}_i\rangle \rightarrow |\mathbf{k}\rangle\), and then sum over all \( \mathbf{k} \) lying in a small cone centered on some \( \mathbf{k}_f \), as in Sec. 14. The physical situation can be visualized as in Fig. 6, which shows the initial and final wave vectors of both particles as seen in the center-of-mass frame.

![Fig. 6. Two-body scattering as seen in the center-of-mass frame. Particle 2 comes in from the left, particle 1 from the right. The initial and final wave vectors of the two particles as seen in the center of mass frame are shown and expressed in terms of the initial and final wave vectors \( \mathbf{k}_i \) and \( \mathbf{k}_f \) of the center-of-mass motion.](image)

Finally, to compute the differential cross section we divide the differential transition rate by the incident flux, defined as \( J = nv \) as in Sec. 13, where \( n = 1/V \) (one incident particle in the box of volume \( V \)), where particle 2 can be thought of as the incident particle, and where \( v = p/\mu \) is the relative velocity. Alternatively, we can think of two particles in a box of volume \( V \), so that \( n_1 = n_2 = 1/V \), whereupon the integral in Eq. (57), taken over the box, gives \((1/V^2)V = 1/V\). The conversion from transition rate to cross section is the same in either case. The final differential cross section is given by Eq. (79), with \( m \) replaced by \( \mu \). As Fig. 6 makes clear, the cross section is measured in the center-of-mass frame.

All of this assumes that the two particles are distinguishable. If they are identical, then it is necessary to use properly symmetrized or antisymmetrized wave functions (including the spin), as discussed in Notes 28. See Prob. 1. In this case one finds interference terms in the cross section between the direct and exchanged matrix elements.

Another point of view is to include the center-of-mass dynamics in the description of the scattering process, that is, to use the entire Hamiltonian (85), including \( H_{\text{CM}} \). In this case we take

\[
H_0 = \frac{\mathbf{p}^2}{2M} + \frac{\mathbf{p}^2}{2\mu}, \quad H_1 = U(r).
\]
The unperturbed eigenstates can be taken to be $|Kk\rangle$, with wave function
\[ \Psi_{Kk}(R, r) = \langle Rr|Kk\rangle = e^{i(K \cdot R + k \cdot r)/V}, \tag{89} \]
which are assumed to have periodic boundary conditions in a box of volume $V$ in both the coordinates $R$ and $r$. The normalization is such that
\[ \int d^3R d^3r |\Psi_{Kk}(R, r)|^2 = 1, \tag{90} \]
where both the $R$ and $r$ integrations are taken over the volume $V$, and the orthonormality relations are
\[ \langle Kk|K'k'\rangle = \delta_{KK'} \delta_{kk'}. \tag{91} \]
The unperturbed energies are
\[ E_{Kk} = \frac{\hbar^2 K^2}{2M} + \frac{\hbar^2 k^2}{2\mu}. \tag{92} \]

The box is a mathematical crutch that allows us to deal with a discrete spectrum, and exactly how we set it up and the boundary conditions we impose are not important as long as $V \to \infty$ gives physical results. In the present case, both $K$ and $k$ are quantized to lie on a lattice, as in Eq. (65). As $V \to \infty$, both $K$ and $k$ take on continuous values.

Now let $|K_i, k_i\rangle$ be an initial state, and $|Kk\rangle$ some final state. Given that $P$ commutes with the entire Hamiltonian $H = H_0 + H_1$, there cannot be any transitions that change the value of $K$, so we must have $c_{Kk}(t) = 0$ if $K \neq K_i$. This is true under the exact time evolution engendered by $H$, and is not a conclusion of perturbation theory. However, we see the same thing in first order perturbation theory if we compute the matrix element of the perturbing Hamiltonian between the initial and final states,
\[ \langle Kk|U(r)|K_i, k_i\rangle = \frac{1}{V^{3/2}} \int d^3R d^3r e^{-i(K - K_i) \cdot R} e^{-i(k - k_i) \cdot r} U(r) = \delta_{K, K_i} \frac{(2\pi)^{3/2}}{V} \tilde{U}(k - k_i), \tag{93} \]
where the $r$-integration is the same as in Eq. (76). Except for the Kronecker delta in the total momentum, it is the same result obtained previously.

The Einstein frequency appearing in the expression for $c^{(1)}_{Kk}(t)$ is
\[ \omega = \frac{\hbar}{2\mu} \left( \frac{K_i^2}{2M} + \frac{k_i^2}{2\mu} - \frac{K^2}{2M} - \frac{k^2}{2\mu} \right), \tag{94} \]
but, in view of the Kronecker delta in Eq. (93), the result is simply
\[ \omega = \frac{\hbar}{2\mu} (k^2 - k_i^2), \tag{95} \]
for states for which $c^{(1)}_{Kk}$ does not vanish. This is just Eq. (67) all over again, with $m$ replaced by $\mu$. The energy of the center-of-mass motion does not change in the scattering process.
Now squaring $c_{KK}(t)$ we get a probability of the transition $|K_ik_i⟩ → |Kk⟩$ in first-order, time-dependent perturbation theory, which we must sum over some collection of final states to get a physically meaningful result. Notice that the square of the Kronecker delta $δ_{K_i}K_i$ is just the same as the original Kronecker delta.

It is best to carry out the sum as follows. Let $R$ be a region of $K$-space, which may or may not contain the initial momentum $K_i$. Then we sum over all final $k$ in a cone as in Figs. 5 or 6, and over all $K$ values in $R$. Dividing the probability by the time $t$, we interpret the result as the transition rate,

$$\int_R d^3K \DeltaΩ \frac{d^5w}{dK^3 dΩ}. \quad (96)$$

Here the 5 on $d^5w$ indicates that $d^3K$ is 3-dimensional and $dΩ$ is 2-dimensional. (By the same logic we should write $d^2w/dΩ$ for the usual differential transition rate instead of $dw/dΩ$, as we have been doing.) This integral can also be interpreted as

$$\int_R d^3K \int_{\text{cone}} dΩ \frac{d^5w}{dK^3 dΩ}, \quad (97)$$

since the cone is small.

When we carry out the same sum on the probabilities, the Kronecker delta $δ_{K_i}K_i$ guarantees that the sum vanishes unless $K_i$ lies in the region $R$. Finally, dividing by the incident flux $v/V$, we can take the limit $V → ∞$ and the result is

$$\int_R d^3K \frac{d^5σ}{dK^3 dΩ} = \begin{cases} 2\pi \frac{\mu^2}{\hbar^2} |\tilde{U}(k_k)|^2, & \text{if } K_i ∈ R \\ 0, & \text{otherwise.} \end{cases} \quad (98)$$

This may be reinterpreted by writing

$$\frac{d^3σ}{dK^3 dΩ} = 2\pi \frac{\mu^2}{\hbar^4} |\tilde{U}(k_k)|^2 δ(Ω - K_i), \quad (99)$$

where the Dirac delta-function shows conservation of the center-of-mass momentum. Integrating this over all $K$, we obtain

$$\int d^3K \frac{d^5σ}{dK^3 dΩ} = \int d^3σ \frac{d^5σ}{dΩ} = 2\pi \frac{\mu^2}{\hbar^4} |\tilde{U}(k_k)|^2, \quad (100)$$

which reproduces our earlier results.

17. Example: The Yukawa Potential

To make an application of Eq. (79), let us choose the Yukawa potential,

$$U(r) = A \frac{e^{-κ r}}{r}, \quad (101)$$

where $A$ and $κ$ are constants. Yukawa invented his potential originally to represent the forces between nucleons. He assumed the nuclear forces were mediated by a boson, the particle that we
now know as the π-meson, which has mass \( M \approx 140 \text{ MeV}/c^2 \). This particle has the Compton wave length

\[
\lambda_C = \frac{\hbar}{Mc} \approx 1.4 \times 10^{-13} \text{ cm},
\]

which is approximately the range of the nuclear forces. The parameter \( \kappa \) in the Yukawa potential is the inverse Compton wavelength,

\[
\kappa = \frac{Mc}{\hbar}.
\]

The Yukawa potential arises as the static solution of the Klein-Gordon equation with a point source, the relativistic wave equation for a spin-0 particle. That is, it is the Green’s function for the time-independent Klein-Gordon equation.

In the limit \( M \to 0 \), the Klein-Gordon equation goes over to the ordinary wave equation, corresponding to the massless photon. Likewise, the Yukawa potential in this limit becomes the Coulomb potential, which is the Green’s function for the Laplace equation, the static limit of the wave equation. The Coulomb potential describes the electromagnetic field produced by a static, point charge, and the Yukawa potential plays a similar role for fields in which the force is mediated by a massive particle. Today we have a much more sophisticated understanding of nuclear forces than in Yukawa’s day, but the Yukawa potential is still useful for modeling purposes.

To apply Eq. (79) we need only compute the Fourier transform, as defined by Eq. (77), of the Yukawa potential. Since the Yukawa potential is rotationally invariant, its Fourier transform is too, so \( \tilde{U}(q) \) depends only on the magnitude \( q = |q| \). Setting \( q = q \hat{z} \), the Fourier transform is easy to evaluate in spherical coordinates. We find

\[
\tilde{U}(q) = \frac{2A}{(2\pi)^{3/2}} \frac{1}{\kappa^2 + q^2}.
\]

Now setting \( q = k - k_i \) (where we now write simply \( k \) instead of \( k_f \) for the final wave vector), we have

\[
q^2 = 4k^2 \sin^2 \theta/2,
\]

where \( \theta \) is the angle between \( k \) and \( k_i \), that is, it is the scattering angle. Then the cross section is

\[
\frac{d\sigma}{d\Omega} = \frac{4A^2m^2}{\hbar^4} \frac{1}{(4k^2 \sin^2 \theta/2 + \kappa^2)^2}.
\]

This result depends on several parameters (\( A, m, \kappa \) and \( k \)), and it is valid only for certain ranges of them. We will examine the validity of this result later, but basically it is valid when the energy of the incident particles is high.

An obvious thing to do with the cross section (106) is to take the limit \( M \to 0 \), that is, \( \kappa \to 0 \), hopefully to obtain the cross section for Coulomb scattering. We may also set \( A = Z_1Z_2e^2 \), so that the potential becomes

\[
U(r) = \frac{Z_1Z_2e^2}{r},
\]
the Coulomb potential for the scattering of two particles of charges $Z_1e$ and $Z_2e$. Then we find

$$\frac{d\sigma}{d\Omega} = \frac{Z_1^2 Z_2^2 e^4 m^2}{4\hbar^4 k^4} \frac{1}{\sin^4 \theta/2} = \frac{Z_1^2 Z_2^2 e^4}{16E^2 \sin^4 \theta/2}$$

(108)

which we recognize as the Rutherford cross section.

The Rutherford cross section is the exact cross section for nonrelativistic, classical scattering of charged particles. It also happens to be the exact cross section for nonrelativistic scattering of distinguishable charged particles in the electrostatic approximation in quantum mechanics, although we have not proved that with our derivation because we have only computed the first term of a perturbation series. To prove that fact, it is necessary to solve the quantum problem of Coulomb scattering exactly, something that can be done by separating the wave equation in confocal parabolic coordinates.

But before we get too excited about having derived the exact answer by the use of perturbation theory, it should be pointed out that the conditions of validity on the formula (79) are not met for any ranges of the parameters. This question is examined in detail in Sec. 37.7. In other words, it is a fluke that the answer came out right. If we compare our results to the exact solution, we find out that although our cross section is exactly correct, the scattering amplitude is completely wrong. But it is wrong only because it has the wrong phase, something that cancels out when we take the square.

The phase of the scattering amplitude becomes important if we consider identical particles, for which the wave function must be composed of properly symmetrized or antisymmetrized wave functions. In this case the scattering amplitude is the sum of two terms, and if we get the phases of the amplitudes wrong, then the cross terms in the expression for the cross section are all wrong.

18. Application: Electrostatic Scattering and Form Factors

Let us consider the scattering of a charged particle by an electrostatic potential created by a charge distribution $\rho(x)$. The charge distribution need not be a point charge; for example, it could be the extended charge distribution inside a proton or a neutron (even though the neutron is neutral, it does contain a nontrivial charge distribution), or it could be the distribution created by the nucleus and the electron cloud of an atom. We denote the charge of the incident particle by $Q$, reserving the symbol $q$ for the quantity $k - k'$, the momentum transfer divided by $\hbar$.

The charge density and electrostatic potential $\Phi(x)$ are related by the Poisson equation,

$$\nabla^2 \Phi(x) = -4\pi \rho(x),$$

(109)

and the potential appearing in the Schrödinger equation is $U(x) = Q\Phi(x)$. The differential cross section (79) requires the Fourier transform $\tilde{U}(q)$ of $U(x)$, a useful expression for which can be obtained by Fourier transforming the Poisson equation. Denoting the variable upon which the Fourier transform depends by $q$, as in Eq. (77), and noting that the operator $-\nabla^2$ in $x$-space
becomes multiplication by $q^2 = |\mathbf{q}|^2$ in $\mathbf{q}$-space, we find
\[ \tilde{\Phi}(\mathbf{q}) = \frac{4\pi}{q^2} \tilde{\rho}(\mathbf{q}), \] (110)
where we use a tilde for the Fourier transform of various quantities. Then the cross section (79) can be written
\[ \frac{d\sigma}{d\Omega} = \frac{4m^2Q^2}{\hbar^4} \frac{1}{q^4} |f(q)|^2, \] (111)
where
\[ f(q) = (2\pi)^{3/2} \tilde{\rho}(q) = \int d^3\mathbf{x} e^{-i\mathbf{q} \cdot \mathbf{x}} \rho(x). \] (112)

See Eq. (105) for an expression for $q^2$.

The function $f$ is called the form factor. In the case of a point charge, $\rho(x) = Ze\delta(x)$, the form factor is simply the constant $f(q) = Ze$, and we obtain the Rutherford cross section. If the charge distribution is extended, then the form factor squared plays the role of a correction factor that converts the Rutherford cross section into the actual cross section (in the approximation inherent in the derivation of Eq. (79)).

Experimental probes of the internal structure of the proton and neutron by electron scattering played an important role in showing that these particles are made up of three constituent point particles, now known as quarks. These experiments were carried out during the 1960’s at the Stanford Linear Accelerator, and many similar experiments, using a variety of incident particles and a variety of targets, have been performed since, accumulating a body of experimental evidence that has guided and confirmed the theory of quantum chromodynamics, the theory of the strong interactions. In these experiments the beam particles are relativistic, so that magnetic effects are important in addition to electric effects. As a result the relativistic treatment of the scattering requires more than one form factor, but the basic ideas are the same as in the nonrelativistic electrostatic model considered here.

For a nonrelativistic application, consider the elastic scattering of electrons by a hydrogen atom. We model the atom as charge distribution described by a point nucleus and an electron cloud with charge density
\[ \rho(x) = -|\psi_{100}(r)|^2 = -\frac{e^{-2r}}{\pi}, \] (113)
where we use Eq. (17.29a) and where we work in atomic units ($m = e = \hbar = 1$). Adding the charge density $\delta(x)$ of the nucleus to this and computing the Fourier transform, we obtain the form factor as
\[ f(q) = 1 - \frac{16}{(q^2 + 4)^2}. \] (114)
When this is used in Eq. (111) we obtain a cross section for electron-hydrogen scattering that is useful at moderately high electron energies (by atomic standards, that is, $E > 1$ or $E \gg 1$ in atomic units).
The scattering of charged particles by atoms is important in calculating \(dE/dx\), the rate at which a charged particle loses energy per unit distance when passing through matter. This is an important problem in experimental high energy physics. In practice the calculations must be relativistic and take into account both elastic and inelastic scattering. At sufficiently high energies, the energy loss for electrons and muons is dominated by bremsstrahlung, the emission of photons as the electron or muon is accelerated in the field of the atomic nucleus.

19. Other Applications

Here are some other applications of time-dependent perturbation theory that we will consider later in the course. As an example of an atom interacting with a classical light wave, we shall study the photoelectric effect in the next set of notes. In the photoelectric effect, a high energy photon, described by a classical light wave, ejects an electron from an atom, leaving behind a positive ion. Later we will consider the emission and absorption of radiation by an atom using the quantized theory of the electromagnetic field, that is, we will study the emission and absorption of photons. A similar example, one that requires second-order time-dependent perturbation theory, is the scattering of photons by matter. Later still we will consider a variety of relativistic processes that are applications of time-dependent perturbation theory, including relativistic scattering of charged particles and the creation and annihilation of electron-positron pairs.

Problems

1. Some questions involving the scattering of identical particles.

(a) In classical mechanics we can always distinguish particles by placing little spots of paint on them. Suppose we have two particles in classical mechanics that are identical apart from insignificant spots of blue and green paint. (The spots have no effect on the scattering.) Suppose the differential cross section in the center-of-mass system for the detection of blue particles is \((d\sigma/d\Omega)(\theta, \phi)\). What is the differential cross section \((d\sigma/d\Omega)_{ac}(\theta, \phi)\) for the detection of particles when we don’t care about the color?

(b) Consider the scattering of two identical particles of spin \(s\) in quantum mechanics. Work in the center-of-mass system, and let \(\mu = m/2\) be the reduced mass. Consider in particular three cases: \(s = 0\), \(s = \frac{1}{2}\), and \(s = 1\). Organize the eigenstates of \(H_0 = p^2/2\mu\) as tensor products of spatial states times spin states; make the spin states eigenstates of \(S^2\) and \(S_z\), where \(S = S_1 + S_2\), and make the spatial states properly symmetrized or antisymmetrized plane waves. Let the initial spin state be \(|S_i M_{S_i}\rangle\) and the final one be \(|S_f M_{S_f}\rangle\). Since potential scattering cannot flip the spin, the cross section will be proportional to \(\delta(S_i, S_f)\delta(M_{S_i}, M_{S_f})\). Find the differential cross section in terms of

\[
\hat{U}_+ = \hat{U}(k_f + k_i), \quad \hat{U}_- = \hat{U}(k_f - k_i),
\]

(115)
where \( \tilde{U} \) is defined as in Eq. (77). Use the fact that \( U(x) = U(-x) \) to simplify the result as much as possible. Use notation like that in Eq. (79).

(c) For the three cases \( s = 0, s = \frac{1}{2}, s = 1 \), assume that the initial state is unpolarized and that we do not care about the final spin state. Find the differential cross section in terms of the quantities \( a = |\tilde{U}_+|^2 \), \( b = |\tilde{U}_-|^2 \), and \( c = \text{Re}(\tilde{U}_+\tilde{U}_-^*) \).

(d) Work out the answer for the case of Coulomb scattering of two electrons, and compare to the classical Rutherford formula, Eq. (108). Express your answer in a notation similar to that of Eq. (108). The cross term you get in applying the results of part (c) to Coulomb scattering is actually incorrect; the trouble is that plane waves do not adequately represent the unbound Coulomb wave functions, which have long range, logarithmic phase shifts. The correct answer is called the Mott cross section, which we will discuss later in class.

2. A basic rule of nonrelativistic interactions is that electrostatic forces cannot flip spins. The reason is that spins respond to magnetic fields, not electric fields. The cross section (79) applies to a charged particle scattered by an electrostatic potential, and in the derivation we assumed that the particle was spinless. But if we had taken spin into account we would have reached the conclusion that the cross section is the same as (79) as long as the final spin state is the same as the initial spin state; and the cross section for flipping the spin is zero. This is under the assumption that the perturbing Hamiltonian is the potential \( H_1 = U(x) \).

If we take into account relativistic corrections, however, then there is a small probability for flipping the spin.

Consider the scattering of an electron by a potential \( U(x) \). Suppose the electron spin of the incident beam is polarized in the +\( \hat{z} \) direction. Including the spin-orbit interaction (24.13), find the differential cross section for electrons polarized in the -\( \hat{z} \) direction after the scattering. Express it as a certain factor times the cross section (79). Notice that \( V \) in Eq. (24.13) is called \( U \) in these notes.

Note: It is common in scattering problems to assume that the incident particles are directed in the \( z \)-direction. We do not want to do that in this problem, since the \( z \)-direction is the direction of polarization of the spin of the incident electrons. Call the incident wave vector \( k_i \) and the final one \( k_f \) or just \( k \), as in these notes. These can be in any direction. Also note the identity (25.23).

3. The \( q^4 = 16k^4\sin^4(\theta/2) \) that appears in the denominator of the Rutherford cross section (108) means that there is a large cross section for scattering by small angles, where the momentum transfer is small. Speaking classically, this is obviously due to the small angle scattering that particles experience at large impact parameters. Since the Coulomb potential dies off only slowly with distance, there is still significant scattering even at large impact parameters.

Let the electrostatic potential of the scatterer be \( \Phi(x) \), as in Sec. 18. If we wish the form factor to suppress the small angle scattering, then we should require that \( f(q) = 0 \) at \( q = 0 \). Show that
this implies that the total charge in the distribution $\rho(\mathbf{x})$ vanishes. This makes sense: if the total charge vanishes, then at large distances there is no Coulomb tail to $\Phi(\mathbf{x})$.

The form factor can be expanded in powers of $\mathbf{q}$ for small $\mathbf{q}$,

$$f(\mathbf{q}) = f(0) + \mathbf{q} \cdot \frac{\partial f(\mathbf{q})}{\partial \mathbf{q}} + \ldots$$  \hspace{1cm} (116)

Show that if the source distribution has no electric dipole moment, then the first order term (proportional to $\mathbf{q}$) vanishes. If the total charge is also zero, then the differential cross section (79) does not diverge at $\mathbf{q} = 0$. In particular, this is true for any rotationally symmetric charge distribution of zero total charge, like that of the hydrogen atom with the form factor (114).