

1) For V a vector space and $U \subset V$ a vector subspace we define a relation

$$v_1 \sim v_2 \text{ if } v_1 - v_2 \in U$$

This is an equivalence relation:

reflexive: $v_1 - v_1 = 0$ and $0 \in U$ because U is a vector subspace. Then

$$v_1 \sim v_1.$$

symmetric: If $v_1 - v_2 \in U$, say $v_1 - v_2 = u_1$, then

$$v_2 - v_1 = -u_1 \text{ and } -u_1 \in U \text{ by assumption. So}$$

$$v_1 \sim v_2 \Leftrightarrow v_2 \sim v_1$$

transitive: Given $v_1 \sim v_2$ and $v_2 \sim v_3$ we have

$$v_1 - v_2 = u_1, \quad v_2 - v_3 = u_2 \quad \text{so}$$

$$(v_1 - v_2) + (v_2 - v_3) = u_1 + u_2$$

$$\Rightarrow v_1 - v_3 = u_3 = u_1 + u_2 \quad \text{by assumption } u_3 \in U$$

so

$$v_1 \sim v_3.$$

We can give V/U the structure of a vector space by defining

$$[v] + [\omega] = [v + \omega]$$

$$\alpha[v] = [\alpha v]$$

We need to show that these definitions are independent of representative. Suppose $v' = v + u_1$, $\omega' = \omega + u_2$ then

$$[v'] + [\omega'] = [v + u_1 + \omega + u_2] = [v + \omega] = [v] + [\omega]. \checkmark$$

Also

$$\alpha[v'] = [\alpha v + \alpha u_1] = [\alpha v] = \alpha[v]. \quad \checkmark$$

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Define the map $\hat{f}: V/\ker f \rightarrow \text{im } f$ by

$$\hat{f}([v]) = f(v)$$

We show that this is an isomorphism (by showing that $\ker \hat{f} = \{[0]\}$ and that \hat{f} is a homomorphism). By assumption $U \subseteq V = \ker f$ and we have $[u] = [0]$, so indeed $\hat{f}([0]) = 0$ and for any other equivalence class we have $f(v) \neq 0$ if $[v] \neq [0]$.

$$\text{So indeed } \ker \hat{f} = \{[0]\}. \text{ Homomorphism: } \hat{f}([v+w]) = \hat{f}([v]+[w]) \\ = f(v+w) = f(v)+f(w) = \hat{f}(v) + \hat{f}(w)$$

To show that, U^\perp , the space perpendicular to $\ker f$, is isomorphic to $V/\ker f$ we can show they have the same dimension.

From our toy index theorem

$$\dim \ker \hat{f} \stackrel{0 \text{ from above}}{=} \dim \text{im } \hat{f} = \dim(V/\ker f)$$

$$\Rightarrow \dim \text{im } \hat{f} = \dim \text{im } f = \dim(V/\ker f)$$

$$\Rightarrow \dim(V/\ker f) = \dim \text{im } f = \dim V - \dim \ker f = \dim V - \dim U$$

On the other hand it's clear that

$$\dim(U^\perp) = \dim V - \dim U$$

so indeed,

$$\dim(V/\ker f) = \dim(U^\perp)$$

To specify the isomorphism simply specify how to map basis vectors in one space onto those of the other.

2) a) Consider the map $r : V^* \rightarrow U^*$ which is given by restriction, $r(\alpha) = \alpha|_U$. Again our linear index theorem gives

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$$\dim \ker r + \dim \text{img } r = \dim V^* = \dim V$$

$$\xrightarrow{\quad \parallel \quad} \quad \parallel$$

$$\dim X^* + \dim U^* = \dim V$$

by assumption

that $\alpha \in X^*$ vanishes on U .

Then,

$$\boxed{\dim X^* + \dim U = \dim V}$$

b) Well we know that the $\ker f$ is a linear subspace of V , what can we say about its annihilator space? Well the annihilator space should be a linear subspace of V^* , so let's guess that it's $\text{img } f^*$ and check if this is true. Let $\ker f = U$ and $X^* = \{ \alpha \in V^* \mid \alpha(u) = 0 \forall u \in U \}$

then for $\beta \in \text{img } f^* \subset V^*$ we have $\beta = f^*(\gamma)$ for some $\gamma \in W^*$

and $\beta(v) = (f^*\gamma)(v) = \gamma(f(v)) = 0 \quad \forall v \in U$ since $f(v) = 0$

for these vectors, so $\text{img } f^* \subset X^*$.

Now, suppose instead $\beta \in X^*$ and define $\gamma \in W^*$ by $\gamma(\omega) = \beta(\omega)$ with $f(\omega) = \omega$. This definition is independent of ω because if we suppose $f(v) = f(v') = \omega$ then $f(v - v') = 0$ and $v - v' \in \ker f$. But then

$$\beta(v') = \beta(v + v' - v) = \beta(v) \text{ because } \beta \in X^*$$

Finally we have $\beta = f^*\gamma$ and so $X^* \subset \text{img } f^*$

Then $\text{img } f^* = X^*$ and from part a) we have,

$$\dim \ker f + \dim \text{img } f = \dim V$$

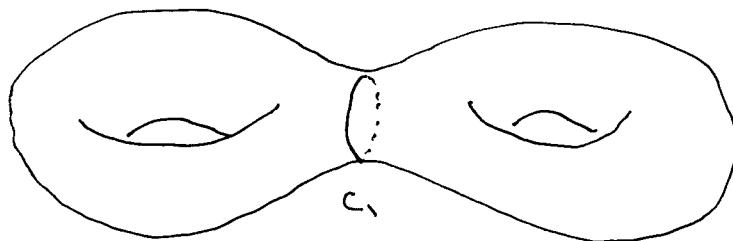
$$\Rightarrow \boxed{\dim \text{img } f = \dim V - \dim \ker f = \dim X^* + \dim \ker f - \dim \ker f = \dim \text{img } f^*}$$

3) We can just check directly that (4) satisfies (5) :

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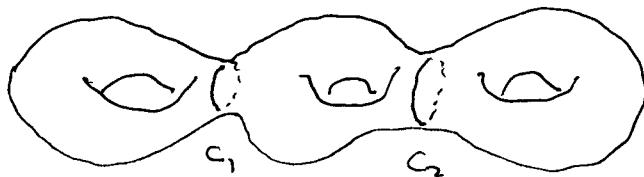
$$\begin{aligned}
 \langle \tilde{f} \omega, v \rangle_g &= \langle (g^{-1} f^* G) \omega, v \rangle_g \\
 &= ((f^* G) \omega, v)^{\text{standard pairing}} \\
 &= (G(\omega), f(v)) \text{ def. of } f^* \\
 &= \langle \omega, f v \rangle_G \checkmark
 \end{aligned}$$

4) a)



The ~~edge~~^{Cycle} c_1 is the boundary of the left or right halves but is not continuously deformable to a point.

b)



The cycles c_1 and c_2 are homologous as they bound the middle handle but cannot be deformed into one another.