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is just the probability density there. However, there are several subtleties to the problem of measuring the phase of  $\psi$ .

One is that the phase of  $\psi$  is not even determined until we specify a convention for the vector potential. This is because when we do a gauge transformation on  $\vec{A}$ ,  $\psi$  changes also:

$$\vec{A}' = \vec{A} + \nabla X \quad X = \text{"gauge scalar"}$$

$$\psi'(\vec{x}) = e^{-\frac{ie}{\hbar c} X(\vec{x})} \psi(\vec{x}).$$

$\psi$  changes by a phase factor that depends on  $\vec{x}$ , thus the phase of  $\psi$  ~~is not~~ cannot be definite without a definite convention for  $\vec{A}$ .

This situation is clarified if we introduce a bundle with  $M = \mathbb{R}^3$  (physical space), ~~and~~  $F = \mathbb{C}$ . This is an example of a Hermitian line bundle. A line

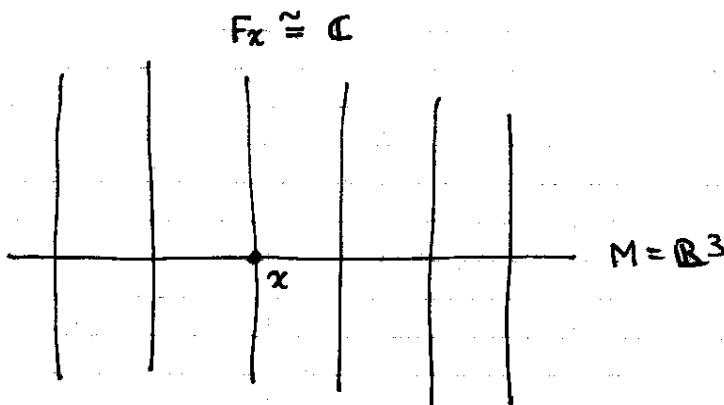
bundle in general

is any ~~line~~

vector bundle

in which

the fibers are



1D vector spaces (real or complex). Here they are complex. The "Hermitian" part means that we introduce a complex metric onto each fiber, that allows us to compute  $|\psi|^2$  at each point  $x$ . Since each fiber has a metric, we restrict consideration to orthonormal frames, so the structure group is  $U(1) = G$ . (We would use  $U(n)$  if  $F = \mathbb{C}^n$ .)

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We ignore the possibility that the individual fibers  $F_x$  might have a natural isomorphism with  $F = \mathbb{C}$ , since on a general bundle there would be none, and think of  $F_x$  as a plane (a 1D complex vector space) with an origin (a 0-vector) but no preferred basis. A basis would consist of one nonzero vector in  $F_x$ ,

call it  $e$ . We choose it to be a unit vector.

Given the basis  $e$ , an arbitrary vector

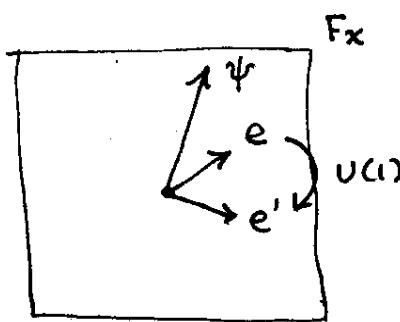
in  $F_x$ , call it  $\psi$ , can be represented as a linear combination of  $e$  with a <sup>complex</sup> coefficient, call it  $\psi(x)$ :

$$\psi = e \psi(x)$$

$\uparrow$                        $\uparrow$   
 abstract                    its component  
 vector                    w.r.t.  $e$ .

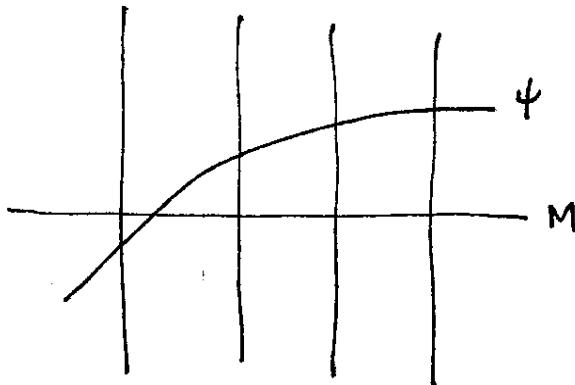
We can of course change basis,  $e \rightarrow e'$  by a  $U(1)$  transformation, whereupon the vector  $\psi$  acquires a new component  $\psi'(x)$ .

We interpret the equation for the transformation of  $\psi$  under a gauge transformation as giving two components,  $\psi(x)$  and  $\psi'(x) \in \mathbb{C}$ , of one abstract vector  $\psi$  w.r.t two different bases  $e$  and  $e'$ , related by the  $x$ -dependent  $U(1)$  phase factor  $e^{-ie\frac{1}{\hbar c}X(x)}$ . Then the quantum state of the particle is represented by a section of the Hermitian line bundle,



$$F = \mathbb{C}$$

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This is a global section, since  $\psi$  should exist everywhere. This is a pleasing picture, because the section does not depend on the gauge.

We must suppose somehow that a field of frames in the frame bundle, called  $e$  or  $e'$  above, is specified once a gauge convention has been chosen for  $\vec{A}$ . The precise manner in which this occurs will be explained later. We just note for now that a section of the frame bundle is in general only locally defined, since a global section of the frame bundle exists iff the frame bundle is trivial. Thus, the wave function  $\psi(x)$  will be only locally defined, in general, even though the section  $\psi$  is global.

In the case that  $M = \mathbb{R}^3$  (or  $\mathbb{R}^4$  for a time-dependent problem), all the bundles discussed above are trivial, since  $\mathbb{R}^3$  or  $\mathbb{R}^4$  is contractible. In the case of a trivial bundle, the global section  $\psi$  can be described by a global wavefunction  $\psi(x)$ , and we return to the usual way of thinking about wavefunctions, as complex-valued fields,

$$\psi: \mathbb{R}^3 \rightarrow \mathbb{C}.$$

A field in the usual sense is just a mapping,

$$\psi: M \rightarrow F$$

where usually  $M \subseteq \mathbb{R}^3$  or  $\mathbb{R}^4$  and  $F$  is the "field value space",

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for example,  $\mathbb{R}^3$  for an electric field  $\vec{E}$ . Thus a field in this case is just a special case of a map between two spaces. Write such a map generally as  $f: A \rightarrow B$ . The map  $f$  can be seen geometrically as the set of points  $(a, b) \in A \times B$  such that  $b = f(a)$ . This is just the graph of the function, but it can also be seen as a section of the trivial fiber bundle  $A \times B$ . Thus, a section of a ~~and~~ possibly nontrivial fiber bundle is a generalization of the usual notion of a function or map between two spaces, or of a field in physical application.

An application where the Hermitian line bundle carrying the section  $f$  is nontrivial occurs when we have a charged particle moving in the field of a magnetic monopole,

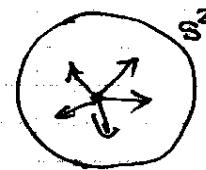
$$\vec{B} = g \frac{\hat{r}}{r^2}.$$

We remove the ~~the~~ origin to avoid the singularity, and set  $M = \mathbb{R}^3 - \{0\}$ . This is not a contractible space. The magnetic field 2-form is

$$B = \frac{1}{2} \epsilon_{ijk} B_i dx^j \wedge dx^k,$$

it satisfies  $dB = 0$ , which is equivalent to  $\nabla \cdot \vec{B} = 0$ . But  $B \neq dA$ , i.e., there does not exist a global, smooth vector potential for  $\vec{B}$ . This is because a closed form is exact iff its integral over all cycles vanishes. But letting  $S^2$  be any sphere surrounding the monopole, we have

$$\int_{S^2} B = 4\pi g,$$



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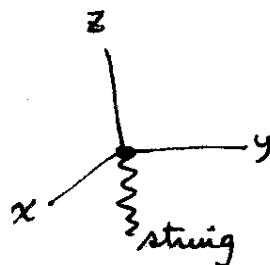
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so  $\vec{B}$  is not exact.

If we write  $\vec{B} = \nabla \times \vec{A}$  in spherical coordinates, it is easy to uncurl  $\vec{B}$  and find  $\vec{A}$ . The solution is not unique, but one that emerges is

$$\vec{A}_N = g \frac{(1-\cos\theta)}{r \sin\theta} \hat{\phi} = g \frac{\tan\theta/2}{r} \hat{\phi}$$

This  $\vec{A}$  is singular on the negative  $z$ -axis, where  $\tan\theta/2 \rightarrow \infty$  and  $\hat{\phi}$  is undefined. But it is smooth on the positive  $z$ -axis, since  $\tan\theta/2 \rightarrow 0$  and the lack of direction of  $\hat{\phi}$  is not a problem. The (half) line of singularities of  $\vec{A}$  (the neg.  $z$ -axis) is called the string of the monopole, although it should be called the string of the vector potential.

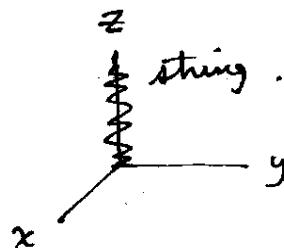


Since this  $\vec{A}$  is smooth and nonsingular over the northern hemisphere, we write  $\vec{A}_N$  for it.

We can get an  $\vec{A}$  that is nonsingular over the southern hemisphere by uncurling  $\vec{B}$  in a slightly different manner. This gives

$$\vec{A}_S = g \frac{(-1-\cos\theta)}{r \sin\theta} \hat{\phi} = -g \frac{\cot\theta/2}{r} \hat{\phi}.$$

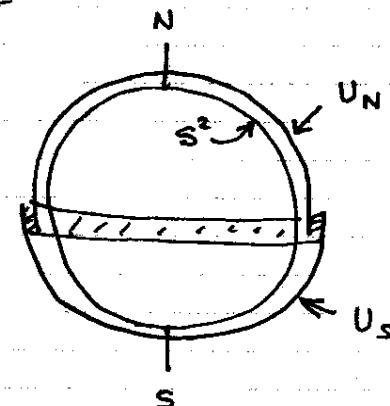
It has a string on the positive  $z$ -axis.



We see that it is necessary to cover  $M = \mathbb{R}^3 - \{0\}$  with at least two charts, with  $\tilde{A}$  smooth in each chart. This suggests that the  $U(1)$  P.F.B. for the charged particle in the monopole field is nontrivial (since a gauge convention somehow is related to a section of this PFB, and apparently this PFB does not have a global section).

The above is motivation to consider  $U(1)$  bundles over  $M = \mathbb{R}^3 - \{0\}$ . Actually, it suffices to study  $U(1)$  bundles over  $S^2$ , since the latter is a deformation retract of  $\mathbb{R}^3 - \{0\}$ . How many (inequivalent) <sup>circle</sup> bundles are there over  $S^2$ ?

We can cover  $S^2$  with two open sets,  $U_N$  which covers the northern hemisphere and extends slightly south of the equator, and  $U_S$  which does something similar from the southern side. These overlap slightly at the equator. If we have any bundle over  $S^2$ , then ~~this~~ the part of this bundle over  $U_N$  or  $U_S$  is trivial, since these are contractible. Thus there exist local trivializations  $\phi_N$  and  $\phi_S$  over these regions.



The overlap  $U_N \cap U_S$  is a small strip around the equator, where  $\varphi$  (the azimuthal angle) is a coordinate. The transition function  $t_{NS} : U_N \cap U_S \rightarrow G = U(1)$  is therefore a function of  $\varphi$ , and we can write

$$t_{NS}(\varphi) = e^{i\alpha} \in U(1)$$

where  $\alpha = \alpha(\varphi)$ . We note that  $t_{NS} : \text{equator} \rightarrow U(1)$ , i.e.,  $t_{NS} : S^1 \rightarrow S^1$ , so  $t_{NS}$  (as a map) belongs to some homotopy class in  $\pi_1(S^1) = \mathbb{Z}$ . The class is characterized by an integer  $n \in \mathbb{Z}$ .

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Now consider a "local gauge transformation" defined by functions

$g_N: U_N \rightarrow G$ ,  $g_S: U_S \rightarrow G$ , taking old transition functions to new ones according to

$$\tilde{\phi}_{N,x} = \phi_{N,x} \circ g_N(x)$$

$$\tilde{\phi}_{S,x} = \phi_{S,x} \circ g_S(x)$$

where  $x \in U_N$  or  $U_S$ . The new transition functions are

$$\tilde{t}_{NS,x} = g_N(x)^{-1} t_{NS,x} g_S(x),$$

where now  $x \in U_N \cap U_S$ , i.e.,  $x \in$  equatorial strip. So we can replace  $x$  by  $\varphi$  in this formula if we want. To what extent can we simplify (or perhaps even transform away) the transition functions by such a gauge transformation? First note, all 3 factors above are elements of  $U(1)$ , an Abelian group, so we can write them in any order. Thus there is no loss of generality in letting  $g_S(x) = e$  and letting  $g_N(\overset{x}{\varphi})$  do all the work.

Look at  $U_N$  from above, where it is like a disk.

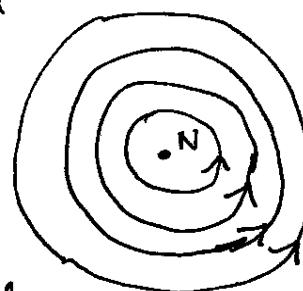
Examine the behavior of  $g_N(x)$  as  $x$  goes around in a circle about the north pole. This gives

a map:  $S^1 \rightarrow U(1) = S^1$ , which has a

homotopy class  $\in \pi_1(S^1) = \mathbb{Z}$ . When the

circle is very small,  $g_N(x)$  is nearly constant,

so the homotopy class is 0. By continuity, this must remain the homotopy class as the circle enlarges to the equator. Therefore on the equator, where we have



$$\tilde{t}_{NS}(\varphi) = g_N(\varphi)^{-1} t_{NS}(\varphi),$$

the homotopy class of  $\tilde{t}_{NS}$  must be the same as that of  $t_{NS}$ .

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We can change  $t_{NS}(\psi)$  into a new function of the same  
homotopy class by means of a gauge transformation, but we cannot  
change it to any other homotopy class. In particular, if  $n \neq 0$ , we  
cannot gauge away  $t_{NS}$ , and the bundle is nontrivial.

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We see that  $U(1)$  bundles over  $S^2$  are characterized by integers  $\in \pi_1(S^1)$ .  
There is an infinite but discrete set of such bundles.

The above analysis leaves two questions unanswered:

- ① How precisely is a choice of gauge for  $\vec{A}$  linked to a choice of section in the PFB associated with the HLB carrying  $\psi$  for the charged particle?
- ② Since there are an  $\infty$  number of  $U(1)$  bundles over  $S^2$ , how do we know which is the right one for  $\psi$ ?

Start today by computing the index (homotopy class of  $\pi_1(S^1)$ ) of the transition function of a specific  $U(1)$  bundle over  $S^2$ , namely, the Hopf map fibration. The summary is the following:

$$\begin{aligned} E = P &= S^3 && (\text{principal fiber bundle}) \\ M &= S^2 \\ F = G &= U(1) \end{aligned}$$

~~definition of a spinor~~ Let  $z = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$  be a 2-component spinor,  $z \in \mathbb{C}^2 = \mathbb{R}^4$ , or if normalized,  $|z|^2 = 1$ , then  $z \in S^3 \subset \mathbb{R}^4$ , as we henceforth assume. The (right) action of  $G$  on  $E$  ( $U(1)$  on  $S^3$ ) is

$$z \mapsto e^{i\alpha} z, \quad z \in S^3, \quad e^{i\alpha} \in U(1).$$

It's just changing the "overall phase" of the spinor. It's conventionally taken to be a right action, but since  $U(1)$  is Abelian you can apply it in any order. The projection  $\pi: S^3 \rightarrow S^3/U(1) = S^2$  is defined by

$\pi(z) = \langle z | \vec{\sigma} | z \rangle =$  "the direction the spinor is pointing in", to use standard QM language. Call this  $\hat{n}(z) \in S^2$ . It's a unit vector. Use coordinates  $(\theta, \varphi)$  on  $S^2$ .

To compute the homotopy class we need transition functions, and to compute those we need local trivializations  $\phi_i$  or  $\phi_{i,x}$ . Notation:

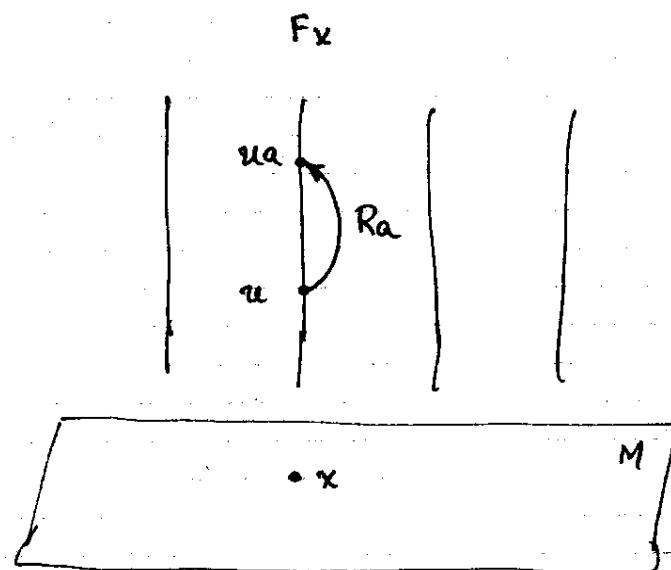
$$\begin{aligned} \phi &= \text{local trivialization} \\ \varphi &= \text{azim.-angle on sphere.} \end{aligned}$$

since there are two ~~two~~ phis.

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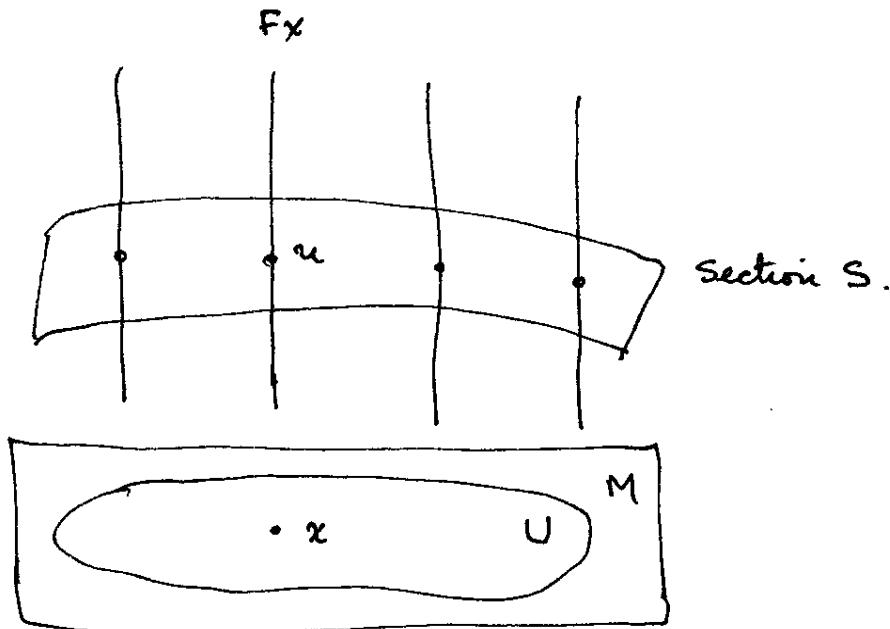
About local tri's in a P.F.B. (in general). The fibers are diffeo to the group  $G$ , but unlike a group they do not have an identity element. But if we take a fiber (over  $x$ , say) and arbitrarily ~~use~~<sup>pick</sup> one point  $u \in F_x$  as a reference point, then all other points of that fiber are accessible (and parameterizable) by means of the group element needed to reach them by right ~~multi~~<sup>the</sup> action of  $G$  on  $P$ .



We denote the right action by  $a \mapsto Ra$ , where  $a \in G$  and  $R_a : P \rightarrow P$ . It satisfies  $R_a R_b = R_{ba}$ , and  $\pi R_a u = \pi u$  (the action is fiber preserving). We denote  $R_a u$  by  $ua$  for short, where  $u \in P$ . In the picture above, point  $u$  on fiber  $F_x$  is identified with  $e \in G$  and  $ua$  with  $a \in G$ . This gives us a map on one fiber,

$$\phi_{i,x} : G \rightarrow F_x : a \mapsto ua.$$

If we choose reference points like  $u$  in the picture above in a smooth manner over some region  $U \subset M$ , then we get a local section of  $P$ , a surface of reference points,



Call the section  $S: U \rightarrow P$ ,  $\pi S(x) = x$ . Then we get an associated local trivialization,

$$\phi: U \times G \rightarrow P : (x, a) \mapsto S(x)a.$$

So on a P.F.B., a local section and a local trivialization imply one another.

For the Hopf map, the choice of a reference point on a fiber,  $x$ , is the same as a phase convention for the normalized spinors pointing in the direction  $x = (\theta, \varphi)$ . And the section  $S$  is a smooth assignment of phase conventions for spinors pointing in directions  $(\theta, \varphi)$  over some region of  $S^2$ .

Let  $z_0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  be the spinor "pointing in" the  $\hat{z}$ -direction, i.e.,  $\langle z_0 | \vec{\sigma} | z_0 \rangle = \hat{z} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . Then a spinor pointing in direction  $(\theta, \varphi)$  can be written down using spin rotation operators,

$$z(\theta, \varphi) = R_z(\varphi) R_y(\theta) z_0,$$

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where the rotation about axis  $\hat{a}$  by angle  $\theta$  is

$$R_{\hat{a}}(\theta) = e^{-i\frac{\theta}{2}\hat{a}\cdot\vec{\sigma}} = \cos\frac{\theta}{2} - i(\hat{a}\cdot\vec{\sigma})\sin\frac{\theta}{2}.$$

so,

$$\begin{aligned} z(\theta, \varphi) &= \begin{pmatrix} e^{-i\varphi/2} & 0 \\ 0 & e^{+i\varphi/2} \end{pmatrix} \begin{pmatrix} \cos\theta/2 & -\sin\theta/2 \\ \sin\theta/2 & \cos\theta/2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} e^{-i\varphi/2} \cos\theta/2 \\ e^{i\varphi/2} \sin\theta/2 \end{pmatrix} \end{aligned}$$

This spinor  ~~$z$~~   $z(\theta, \varphi)$  points in the  $(\theta, \varphi)$  direction, but it is not continuous over the whole sphere, mainly due to the  $\frac{\pi}{2}$  angle  $\varphi/2$  which gives a discontinuity on the line  $\varphi=0$ . We can get rid of this by multiplying by  $e^{i\varphi/2}$  (a change in phase convention) to obtain the spinor

$$z_N(\theta, \varphi) = \begin{pmatrix} \cos\theta/2 \\ e^{i\varphi} \sin\theta/2 \end{pmatrix}.$$

This spinor is smooth everywhere on  $S^2$  except at the south pole, where  $e^{i\varphi}$  represents oscillations of finite amplitude that take place over a smaller and smaller region as  $\theta \rightarrow \pi$ . Thus the spinor is not differentiable at the south pole. The similar problem does not occur at the north pole, because  $\sin\theta/2 \rightarrow 0$  there. So we call this spinor  $z_N$  to indicate that it is smooth over the northern hemisphere.