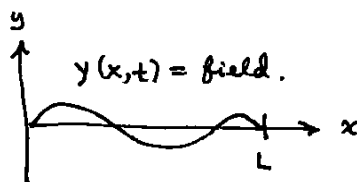


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Summary.

1D Vibrating String.



$$A[y(x,t)] = \int dt L = \int dx dt \mathcal{L}. \quad L = \int dx \mathcal{L}$$

$$\mathcal{L} = \frac{\rho}{2} \left(\frac{\partial y}{\partial t} \right)^2 - \frac{\kappa}{2} \left(\frac{\partial y}{\partial x} \right)^2.$$

Generalize:

Write ψ instead of y

write $x \rightarrow \vec{x}$ (3D)

Let $\mathcal{L} = \mathcal{L} \left(\frac{\partial \psi}{\partial t}, \nabla \psi, \psi \right)$

↑ depends on ψ as well as its deriv's.

$$A = \int dt L = \int dt d^3\vec{x} \mathcal{L} = \int d^4x \mathcal{L}.$$

Hamilton's principle:

$$\psi(\vec{x}, t) \rightarrow \psi(\vec{x}, t) + \delta\psi(\vec{x}, t)$$

$$\delta A = A[\psi(\vec{x}, t) + \delta\psi(\vec{x}, t)] - A[\psi(\vec{x}, t)]$$

$$= \int d^4x \mathcal{L}(\psi + \delta\psi, \frac{\partial \psi}{\partial t} + \frac{\partial}{\partial t}(\delta\psi), \nabla\psi + \nabla(\delta\psi)) - \int d^4x \mathcal{L}(\psi, \frac{\partial \psi}{\partial t}, \nabla\psi) =$$

$$\rightarrow \int d^4x \left[\frac{\partial \mathcal{L}}{\partial \psi} - \frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial (\frac{\partial \psi}{\partial t})} \right) - \nabla \cdot \left(\frac{\partial \mathcal{L}}{\partial (\nabla \psi)} \right) \right] \delta\psi + \text{bdry terms}$$

↑
argue away

$$\rightarrow \int d^4x \left[\frac{\partial \mathcal{L}}{\partial \psi} + \frac{\partial \mathcal{L}}{\partial (\frac{\partial \psi}{\partial t})} \frac{\partial}{\partial t}(\delta\psi) + \frac{\partial \mathcal{L}}{\partial (\nabla \psi)} \cdot \nabla(\delta\psi) \right]$$

(integrate by parts)

$$\rightarrow = 0 \text{ demand for all } \delta\psi \Rightarrow$$

$$\boxed{\frac{\partial \mathcal{L}}{\partial \psi} = \frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial (\frac{\partial \psi}{\partial t})} \right) + \nabla \cdot \left(\frac{\partial \mathcal{L}}{\partial (\nabla \psi)} \right)}$$

3+1 version

Euler-Lagrange eqns for $\mathcal{L}(\psi, \frac{\partial \psi}{\partial t}, \nabla \psi)$.

Apply to vibrating string. Change notation, $\psi \rightarrow y$
 $\vec{z} \rightarrow x$ (ID now).

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notice \mathcal{L} does not depend on y ,

$$\mathcal{L} = \mathcal{L} \left(\frac{\partial y}{\partial t}, \frac{\partial y}{\partial x} \right).$$

Thus
$$0 = \frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial \left(\frac{\partial y}{\partial t} \right)} \right) + \frac{\partial}{\partial x} \left(\frac{\partial \mathcal{L}}{\partial \left(\frac{\partial y}{\partial x} \right)} \right)$$

OR
$$0 = \frac{\partial}{\partial t} \left(\rho \frac{\partial y}{\partial t} \right) + \frac{\partial}{\partial x} \left(-\kappa \frac{\partial y}{\partial x} \right)$$

OR
$$0 = \rho \frac{\partial^2 y}{\partial t^2} - \kappa \frac{\partial^2 y}{\partial x^2}$$

OR
$$\frac{\partial^2 y}{\partial x^2} - \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2} = 0 \quad \text{wave eqn. } v = \sqrt{\frac{\kappa}{\rho}}.$$

Rewrite E-L Eqs in 4-vector notation. $x^\mu = (ct, \vec{x})$.

$$\mathcal{L} = \mathcal{L}(\psi, \partial_\mu \psi).$$

Then
$$\frac{\partial \mathcal{L}}{\partial \psi} = \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \psi)} \right) \quad \text{RHS is a 4-divergence.}$$

The field ψ and Lagr. density \mathcal{L} don't have to be relativistic, but if they are it's nice that E-L eqns automatically emerge in covariant form.

Now look at relativistic scalar field (good practice before tackling EM field).

let $\psi = \psi(\vec{x}, t) = \psi(x^\mu)$. $x^\mu = (ct, \vec{x})$.

Let
$$\mathcal{L} = \frac{1}{2} (\partial_\mu \psi)(\partial^\mu \psi) - \frac{\mu^2}{2} \psi^2.$$

$$\hookrightarrow = \frac{1}{2} \left[\frac{1}{c^2} \left(\frac{\partial \psi}{\partial t} \right)^2 - |\nabla \psi|^2 \right] \quad \text{just like vibrating string.}$$

$$\mu = \frac{mc}{\hbar} = \frac{1}{\lambda_c}, \quad \lambda_c = \text{Compton wavelength of particle.}$$

Work out EL equs from \mathcal{L} :

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$$\frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} = \partial^\mu \psi, \quad \frac{\partial \mathcal{L}}{\partial \psi} = -\mu^2 \psi.$$

So, EL equs are

$$\partial_\mu \partial^\mu \psi + \mu^2 \psi = 0$$

$$\text{or } (\square + \mu^2) \psi = 0$$

If $\mu = 0$, it's the wave eqn, as for light waves, but a scalar field.

If $\mu \neq 0$, it's the Klein-Gordon eqn, the relativistic Schrödinger eqn. for a relativistic, free, spinless particle.

If the photon had mass, you would have μ^2 terms in Maxwell's eqns. too.

Conserved Quantities in field theory are usually associated with currents. Consider for example charge. $J^\mu = \begin{pmatrix} c\rho \\ \vec{J} \end{pmatrix}$,

$$\partial_\mu J^\mu = \frac{\partial \rho}{\partial t} + \nabla \cdot \vec{J}.$$

$$Q = \text{total chg at time } t = \int_{\text{all space}} d^3\vec{x} \rho(\vec{x}, t).$$

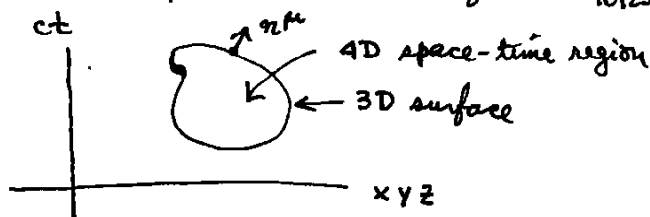
$$\text{So } \frac{dQ}{dt} = \int d^3\vec{x} \frac{\partial \rho}{\partial t} = - \int d^3\vec{x} \nabla \cdot \vec{J} = - \int_{\text{surf.}} da \vec{J} \cdot \hat{n} = 0$$

If we assume $\vec{J} \rightarrow 0$ at spatial ∞ .

④

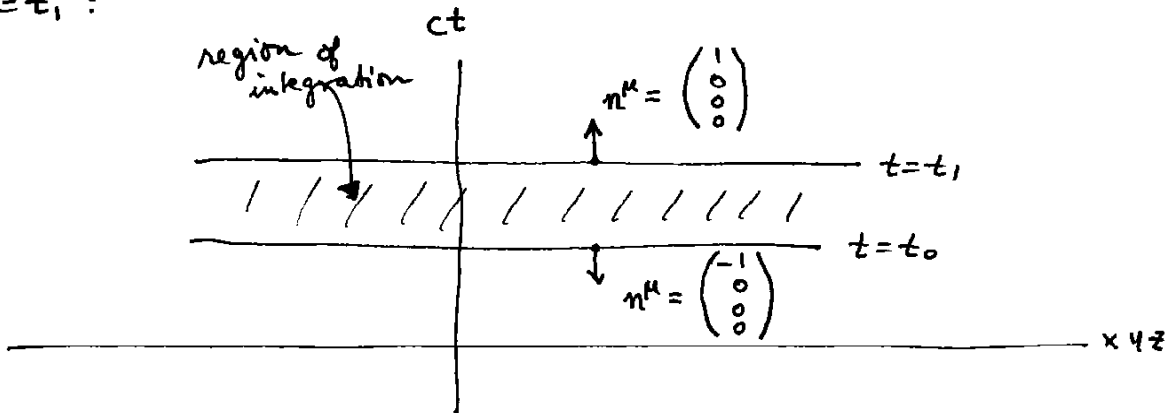
It's interesting that this can also be expressed in terms of a 4-dim'l version of Gauss' thm.

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$$0 = \int_{\text{4D region}} d^4x (\partial_\mu J^\mu) = \int_{\text{surf.}} d^3s J_\mu n^\mu \quad n^\mu = \text{unit vector normal to surface.}$$

Now let 4D region be region between 2 const time slices, $t=t_0$ and $t=t_1$:



$$\text{Then } 0 = \int_{\text{all space}} d^3\vec{x} J_0(t_1, \vec{x}) - \int_{\text{all space}} d^3\vec{x} J_0(t_0, \vec{x}).$$

But since $J_0 = c\rho$, this gives $Q_1 = Q_0$, charge conserved.

Now Noether's Thm in Field Theory

Like $q \rightarrow Q(q, \epsilon)$, write

$\psi(x) \rightarrow \Psi(x, \epsilon)$ for fields. Old field goes to new field.

What is a "symmetry"? Don't demand that \mathcal{L} is invariant,

$$\mathcal{L}(\Psi, \partial_\mu \Psi) = \mathcal{L}(\psi, \partial_\mu \psi) \quad (\text{too strong}).$$

Instead demand,

$$\mathcal{L}(\Psi, \partial_\mu \Psi) = \mathcal{L}(\psi, \partial_\mu \psi) + (\partial_\mu G^\mu)$$

↖ a 4-divergence

because this leaves EOM's invariant. This is because,

like term $\frac{dG}{dt}$ for discrete Lagrangians

$$A = \int d^4x \mathcal{L} \rightarrow \text{itself} + \underbrace{\int d^4x (\partial_\mu G^\mu)}$$

↳ = bdry terms by 4D Gauss' thm.

Condition $\delta A = 0$ (Ham's principle) not changed by bdry terms.

Instead of trying to derive general Noether's thm. for fields, just look at space-time translations, so

$$\Psi(x, \epsilon) = \psi(x - \epsilon a) = \psi(x) - \epsilon a^\nu (\partial_\nu \psi)$$

small ϵ .
 $a^\nu =$ some const vector.

Now suppose \mathcal{L} has no explicit x^μ -dependence,

$$\mathcal{L} = \mathcal{L}(\psi, \partial_\mu \psi) \quad \text{but not } \mathcal{L} = \mathcal{L}(\psi, \partial_\mu \psi, x).$$

Then

$$\begin{aligned} \mathcal{L}(\Psi, \partial_\mu \Psi) &= \mathcal{L}(\psi - \epsilon a^\nu (\partial_\nu \psi), \partial_\mu \psi - \epsilon a^\nu (\partial_\nu \partial_\mu \psi)) \\ &= \mathcal{L}(\psi, \partial_\mu \psi) - \epsilon a^\nu \left(\underbrace{\frac{\partial \mathcal{L}}{\partial \psi} (\partial_\nu \psi) + \frac{\partial \mathcal{L}}{\partial (\partial_\mu \psi)} (\partial_\nu \partial_\mu \psi)} \right). \end{aligned}$$

Q: so this term () a 4-divergence?