

**Physics 209**  
**Fall 2002**  
**Homework 9**  
**Due Saturday, November 1 at 5:00pm.**

**Note:** Due to the exam in 221A, this homework is due on Saturday, November 1 instead of Friday, October 31. However, the building is only open during limited hours on Saturday. If you do not have a key, you will have to make arrangements to have your homework delivered on time, or else turn it in on Friday.

1. In class we derived the 3 + 1 version of the relativistic Lagrangian for a particle in a given electric and magnetic field,

$$L(\mathbf{x}, \dot{\mathbf{x}}) = -mc^2 \sqrt{1 - |\dot{\mathbf{x}}|^2/c^2} - e\Phi + \frac{e}{c} \dot{\mathbf{x}} \cdot \mathbf{A}. \quad (1)$$

(a) Show that the Euler-Lagrange equations give the correct equations of motion.

(b) Show that this Lagrangian is regular (you can solve for  $\dot{\mathbf{x}}$  in terms of  $\mathbf{p}$ ), and find the Hamiltonian  $H(\mathbf{x}, \mathbf{p})$

(c) Show that Hamilton's equations give the correct equations of motion.

2. Noether's theorem for Lagrangians  $L(q, \dot{q})$  was described in class as follows. We let  $q \rightarrow Q(q, \epsilon)$  be a mapping of configuration space onto itself. We say that this mapping is a *symmetry* of the Lagrangian if

$$L\left(Q(q, \epsilon), \frac{dQ(q, \epsilon)}{dt}\right) = L(q, \dot{q}) + \frac{d\Lambda(q, \epsilon)}{dt} \quad (2)$$

for some function  $\Lambda$ , where  $q, Q$  etc are abbreviations for multicomponent coordinate vectors,  $q_i, Q_i$ , etc. Also, in Eq. (2)  $dQ/dt$  and  $d\Lambda/dt$  are abbreviations for

$$\frac{dQ_i(q, \epsilon)}{dt} = \sum_j \frac{\partial Q_i}{\partial q_j} \dot{q}_j \quad (3)$$

and

$$\frac{d\Lambda(q, \epsilon)}{dt} = \sum_i \frac{\partial \Lambda}{\partial q_i} \dot{q}_i, \quad (4)$$

so that the Lagrangian before and after the transformation is a function of  $q$  and  $\dot{q}$ . Equation (2) means that the equations of motion are the same before and after the symmetry transformation.

As explained in class, we only use this symmetry property for infinitesimal  $\epsilon$ , which means we expand out to first order in  $\epsilon$  to obtain an identity involving the Lagrangian, or else we differentiate Eq. (2) with respect to  $\epsilon$  and set  $\epsilon = 0$ , which is the same thing. This gives the identity,

$$\sum_i \left( \frac{\partial L}{\partial q_i} F_i + \frac{\partial L}{\partial \dot{q}_i} \frac{dF_i}{dt} \right) = \frac{dG}{dt}, \quad (5)$$

where

$$F_i(q) = \left. \frac{\partial Q_i(q, \epsilon)}{\partial \epsilon} \right|_{\epsilon=0}, \quad (6)$$

and

$$G(q) = \left. \frac{\partial \Lambda(q, \epsilon)}{\partial \epsilon} \right|_{\epsilon=0}. \quad (7)$$

Equation (5) is just an identity satisfied by the Lagrangian, due to the symmetry. But now we use the Euler-Lagrange equations,

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right) = \frac{\partial L}{\partial q_i}, \quad (8)$$

to write Eq. (5) in the form,

$$\frac{d}{dt} \left( \sum_i F_i p_i - G \right) = 0. \quad (9)$$

This gives us the conserved quantity corresponding to the symmetry.

(a) Consider the relativistic motion of a charged particle of charge  $e$  in a constant, uniform magnetic field,  $\mathbf{B} = B_0 \hat{\mathbf{z}}$ . Use the covariant Lagrangian,

$$L \left( x^\mu, \frac{dx^\mu}{d\sigma} \right) = mc \sqrt{\frac{dx^\mu}{d\sigma} \frac{dx_\mu}{d\sigma}} - \frac{eB_0}{c} x \frac{dy}{d\sigma}, \quad (10)$$

where as explained in class  $t$  is regarded as a 4th  $q$  and  $\sigma$  is an arbitrary parameter of the orbits. Equation (10) effectively uses the vector potential,  $\mathbf{A} = B_0 x \hat{\mathbf{y}}$ . Find the constants of motion associated with translations in the  $x$ ,  $y$ ,  $z$  and  $t$  directions. Find the constant of motion associated with rotations in the  $x$ - $y$  plane. Express your constants of motion in terms of the kinetic (not canonical) momentum, or equivalently in terms of the world velocity. Show that the constants associated with  $x$  and  $y$  displacements are closely related to the guiding center position.

Notational suggestion: Since the covariant, kinetic 4-momentum  $p_\mu$  has components,

$$p_\mu = \begin{pmatrix} E/c \\ -\mathbf{p} \end{pmatrix}, \quad (11)$$

use the notation  $p_1, p_2, p_3$  for  $p_\mu$  with  $\mu = 1, 2, 3$ , and  $p_x, p_y, p_z$  for the usual components of  $\mathbf{p}$ , so that  $p_x = -p_1$ , etc.

(b) This is probably the hardest part of this homework, so you might want to do it last. Consider the motion of a nonrelativistic charged particle of charge  $e$  in the field of a magnetic monopole,

$$\mathbf{B}(\mathbf{x}) = g \frac{\mathbf{x}}{r^3}, \quad (12)$$

where  $g$  is the strength of the monopole and  $r = |\mathbf{x}|$ . Assume the monopole is infinitely massive and located at the origin. The nonrelativistic Lagrangian for this system is

$$L = \frac{m}{2} |\dot{\mathbf{x}}|^2 + \frac{e}{c} \dot{\mathbf{x}} \cdot \mathbf{A}(\mathbf{x}), \quad (13)$$

where  $\mathbf{B} = \nabla \times \mathbf{A}$ . It is possible to work out explicit formulas for  $\mathbf{A}$  which produce the magnetic field (12), but the formulas are ugly, so we will not attempt to do that. Instead, we will just use the property  $\mathbf{B} = \nabla \times \mathbf{A}$ , with  $\mathbf{B}$  given by Eq. (12).

Consider rotations about the axis  $\hat{\mathbf{n}}$ , so that for small angles of rotation  $\theta$ ,  $\mathbf{x}$  is replaced by  $\mathbf{x} + \theta(\hat{\mathbf{n}} \times \mathbf{x})$ . Show that such rotations are a symmetries of the Lagrangian (13), and find the corresponding vector of conserved quantities (a vector since  $\hat{\mathbf{n}}$  is arbitrary). Hint: the conserved quantities will be gauge-invariant, that is, you should be able to find an expression for them that does not involve  $\mathbf{A}$ .

**3.** Fermat's principle in optics says that light rays  $\mathbf{x}(\lambda)$  are stationary paths of the following functional, the "optical path,"

$$P[\mathbf{x}(\lambda)] = c \int dt = \int_{\lambda_0}^{\lambda_1} n(\mathbf{x}) ds = \int_{\lambda_0}^{\lambda_1} n(\mathbf{x}) \left| \frac{d\mathbf{x}}{d\lambda} \right| d\lambda, \quad (14)$$

where  $n(\mathbf{x})$  is the index of refraction,  $\mathbf{x} = (x, y, z)$ , and  $\lambda$  is an arbitrary parameter.

Suppose the medium is one in which  $n(\mathbf{x})$  only depends on  $z$ , so that the system has translational symmetry in the  $x$ - and  $y$ -directions. For example, we might have a discontinuous change from one medium to another, with the interface being at  $z = \text{const}$ . Show that Snell's law is a consequence of Noether's theorem.

4. In class we modelled the transverse vibrations of a string as a discrete set of  $N$  masses  $m$  spaced at intervals of  $\Delta x$  with Lagrangian,

$$L = \sum_{i=1}^N \frac{m}{2} \dot{y}_i^2 - \sum_{i=1}^{N+1} \frac{k}{2} (y_i - y_{i-1})^2, \quad (15)$$

where  $k$  is the spring constant for the spring connecting mass  $i$  and mass  $i - 1$ . All springs have the same  $k$ . Then we took the limit in which  $N \rightarrow \infty$ ,  $m = \rho \Delta x$ ,  $k = \kappa / \Delta x$ , where  $\rho$  is the mass per unit length of the string and  $\kappa$  is the spring constant of the whole string times the length of the string. This gave the field Lagrangian,

$$L = \int dx \mathcal{L}, \quad (16)$$

where the Lagrangian density is

$$\mathcal{L} = \frac{\rho}{2} \left( \frac{\partial y}{\partial t} \right)^2 - \frac{\kappa}{2} \left( \frac{\partial y}{\partial x} \right)^2. \quad (17)$$

Construct the classical Hamiltonian  $H$  for the discretized version of the vibrating string. Take the limit  $N \rightarrow \infty$  and show that  $H$  can be written as the  $x$  integral of a Hamiltonian density  $\mathcal{H}$ , and find an expression for  $\mathcal{H}$ . The Hamiltonian density  $\mathcal{H}$  is interpreted as the energy density of the system.

Show that there exists a function  $S$ , depending on  $y(x, t)$  and/or its various derivatives, such that

$$\frac{\partial \mathcal{H}}{\partial t} + \frac{\partial S}{\partial x} = 0. \quad (18)$$

This is a one-dimensional continuity equation, and  $S$  is interpreted as the energy flux of the system (like the Poynting vector in electromagnetism).