

1)

$$\vec{F} = q (\vec{E} + \vec{v} \times \vec{B}) \quad \text{in frame } \mathcal{F}$$

$$\vec{F}' = q (\vec{E}' + \vec{v}' \times \vec{B}') \quad \text{in frame } \mathcal{F}'$$

(moving at v_0 respect
to \mathcal{F})

$$\vec{v}' = \vec{v} - \vec{v}_0 \quad \leftarrow$$

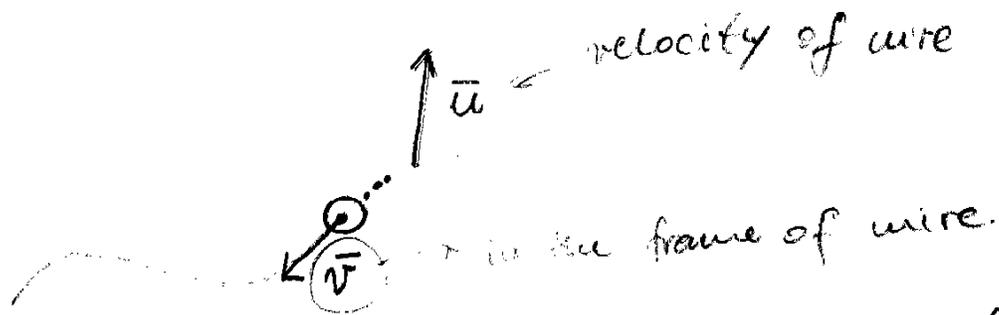
as both are inertial frames $\vec{F} = \vec{F}'$ (Galileo)

so:

$$\begin{aligned} \vec{F} &= q (\vec{E}' + (\vec{v} - \vec{v}_0) \times \vec{B}') \\ &= q (\vec{E}' - (\vec{v}_0 \times \vec{B}') + \vec{v} \times \vec{B}') \\ &= q \left(\underbrace{\vec{E}' - (\vec{v}_0 \times \vec{B}')}_{\vec{E}} + \vec{v} \times \vec{B}' \right) \end{aligned}$$

$\vec{E}' = \vec{E} + \vec{v}_0 \times \vec{B}$ $\vec{B}' = \vec{B}$
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2)



magnetic force over electrons

$$F_{mag}^{e^-} = \sum q_i [(\vec{v}_i + \vec{u}) \times \vec{B}]$$

magnetic force over ions:

$$F_{mag}^{ions} = \sum Q_i (\vec{u} \times \vec{B})$$

Total magnetic work:

~~$W_{mag}^{e^-}$~~

$$W_{mag} = \underbrace{\sum q_i [(\vec{v}_i + \vec{u}) \times \vec{B}] \cdot (\vec{v}_i + \vec{u})}_{\ominus} + \underbrace{\sum Q_i (\vec{u} \times \vec{B}) \cdot \vec{u}}_{\ominus}$$

$W_{mag} = \ominus$ and this is a general rule.

2) b) In equilibrium

$$\begin{cases} \bar{F}_{w_i}^{e^-} + \bar{F}_{E_i}^{e^-} + \bar{F}_{B_i}^{e^-} + \bar{F}_{R_i}^{e^-} = \bar{0} \\ \bar{F}_{w_i}^{ion} + \bar{F}_{E_i}^{ion} + \bar{F}_{B_i}^{ion} + \bar{F}_{R_i}^{ion} = \bar{0} \end{cases}$$

and $\bar{F}_{w_i}^{e^-}$ is a constrain force that forces the electrons to move along the wire; so:

$$\bar{F}_{w_i}^{e^-} = - \left[\underbrace{\bar{F}_{E_i}^{e^-} + \bar{F}_{B_i}^{e^-} + \bar{F}_{R_i}^{e^-}}_{-\bar{F}_{w_i}^{e^-}} - \underbrace{\left(\bar{F}_{E_i}^{e^-} + \bar{F}_{B_i}^{e^-} + \bar{F}_{R_i}^{e^-} \right)}_{\bar{F}_{w_i}^{e^-}} \cdot \hat{l} \hat{l} \right]$$

$$\downarrow$$

$$\cancel{\bar{F}_{w_i}^{e^-}} = + \cancel{\bar{F}_{w_i}^{e^-}} - \bar{F}_{w_i}^{e^-} \cdot \hat{l} \hat{l} \Rightarrow \boxed{\bar{F}_{w_i}^{e^-} \cdot \hat{l} = 0}$$

but the velocity of electrons (in the frame of wire)

$$\bar{v}_i \parallel \hat{l} \Rightarrow \text{so } \bar{F}_{w_i}^{e^-} \cdot \bar{v}_i = 0$$

$$\text{so } \bar{F}_{w_i}^{e^-} \cdot (\bar{u} + \bar{v}_i) = \bar{F}_{w_i}^{e^-} \cdot \bar{u}$$

$$\begin{aligned} &= -\bar{F}_{E_i}^{e^-} \cdot \bar{u} = \bar{F}_{B_i}^{e^-} \cdot \bar{u} - \bar{F}_{R_i}^{e^-} \cdot \bar{u} \\ &= -q_i \bar{E} \cdot \bar{u} + q_i (\bar{u} + \bar{v}_i) \times \bar{B} \cdot \bar{v}_i - \bar{F}_{R_i}^{e^-} \cdot \bar{u} \end{aligned}$$

remember that $\bar{F}_{B_i}^{e^-} \cdot (\bar{u} + \bar{v}_i) = 0$
 $\bar{F}_{B_i}^{e^-} \cdot \bar{u} = -\bar{F}_{B_i}^{e^-} \cdot \bar{v}_i$

for ions

$$\vec{F}_{\text{ext},i}^{\text{ion}} \cdot \vec{u} = -Q_i \vec{E} \cdot \vec{u} - Q_i (\vec{u} \times \vec{B}) \cdot \vec{u} - \vec{F}_{Ri}^{\text{ion}} \cdot \vec{u}$$

the work done by constraints is:

$$\frac{dW^c}{dt} = \sum_i q_i \vec{E} \cdot \vec{u} + q_i ((\vec{u} + \vec{v}_i) \times \vec{B}) \cdot \vec{v}_i - \vec{F}_{Ri}^{e^-} \cdot \vec{u} + \sum_i -Q_i \vec{E} \cdot \vec{u} - \vec{F}_{Ri}^{\text{ion}} \cdot \vec{u}$$

because of neutrality

~~zero~~ because

$$\sum_i \vec{F}_{Ri}^{\text{ion}} + \vec{F}_{Ri}^{e^-} = 0$$

(is an internal force)

$$W_{\text{constraint}} = \sum_i +q_i (\vec{u} \times \vec{B}) \cdot \vec{v}_i + \underbrace{(+q_i) (\vec{v}_i \times \vec{B}) \cdot \vec{v}_i}_{=0}$$

$$\left(\frac{dW}{dt}\right)_{\text{constraint}} = \sum_i +q_i (\vec{u} \times \vec{B}) \cdot \vec{v}_i \rightarrow \text{in a portion of wire}$$

$$\left(\frac{dW}{dt}\right)^c = +I \oint (\vec{u} \times \vec{B}) \cdot d\vec{l} \rightarrow \text{along the circuit}$$

$$\left(\frac{dW}{dt}\right)^{\text{total}} = \left(\frac{dW}{dt}\right)^E + \left(\frac{dW}{dt}\right)^B + \left(\frac{dW}{dt}\right)^c + \left(\frac{dW}{dt}\right)^R \rightarrow 0 \text{ because is an internal force.}$$

$$\left(\frac{dW}{dt}\right)^{\text{total}} = I \oint (\vec{E} + \vec{u} \times \vec{B}) \cdot d\vec{l}$$

4) a) In some gauge

$$\vec{B} = \vec{\nabla} \times \vec{A} \quad \text{with} \quad \nabla^2 \vec{A} = -\vec{J} 4\pi$$

i.e.

$$\left\{ \begin{array}{l} * \nabla^2 A_x = -J_x 4\pi \quad (1) \\ \nabla^2 A_y = -J_y 4\pi \quad (2) \\ \nabla^2 A_z = -J_z 4\pi \quad (3) \end{array} \right.$$

$$B_x|_{z=0} = 0 \Rightarrow \partial_y A_z|_{z=0} - \partial_z A_y|_{z=0} = 0 \quad (A)$$

$$B_y|_{z=0} = 0 \Rightarrow \partial_z A_x|_{z=0} - \partial_x A_z|_{z=0} = 0 \quad (B)$$

since $B_z|_{z=0} \neq 0$ is given by the functional dependence of $A_x(x, y; z=0)$ and $A_y(x, y; z=0)$ only

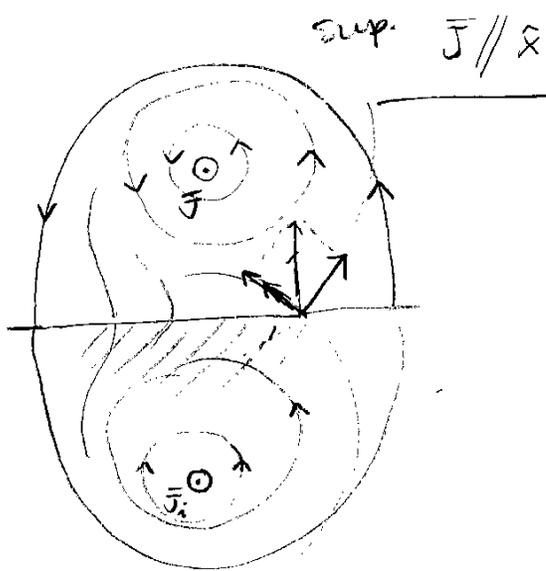
we can add the condition $A_z|_{z=0} = 0$ which is a Dirichlet condition for (3)

$$\text{More over } A_z|_{z=0} = 0 \Rightarrow \left\{ \begin{array}{l} \partial_y A_z|_{z=0} = 0 \\ \text{and } \partial_x A_z|_{z=0} = 0 \end{array} \right.$$

so (A) and (B) become Neumann conditions of (1) & (2)

$\Rightarrow \vec{A}$ is unique (within the gauge and arbitrary b.c.) $\Rightarrow \vec{B}$ is absolutely unique

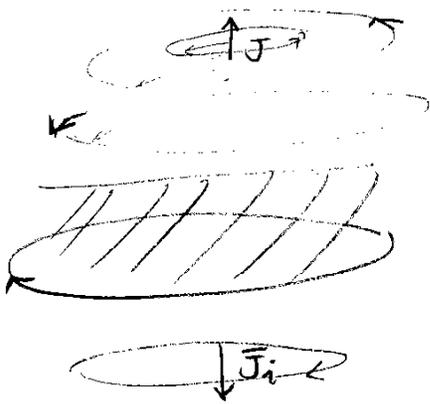
4) ~~a)~~ a)



sup. $\vec{J} // \hat{x} \Rightarrow \vec{J}_i = \vec{J}$

$$\vec{J}_{i//}(x, y, -z) = \vec{J}_{//}(x, y, z)$$

sup. $\vec{J} // \hat{z}$



← magnetic field created by this differential current has only \hat{x} and \hat{y} components over the plane so

\vec{J}_i must cancel completely the magnetic field in the plane (i.e. the

← image current is ~~in~~ in the ~~other~~ other direction)

$$\vec{J}_{i\perp}(x, y, -z) = \vec{J}_{\perp}(x, y, z)$$

by superposition the general image current \vec{J}_i is

$$\vec{J}_{i//}(x, y, -z) = \vec{J}_{//}(x, y, z)$$

$$\vec{J}_{i\perp}(x, y, -z) = \vec{J}_{\perp}(x, y, z)$$

$J_{ix}(x, y, -z) = J_x(x, y, z)$ $J_{iy}(x, y, -z) = J_y(x, y, z)$ $J_{iz}(x, y, -z) = -J_z(x, y, z)$
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Notation: $\vec{J}_i(\vec{r}) = \vec{J}(\vec{r} - 2\vec{r} \cdot \hat{n}) - 2\vec{J}(\vec{r} - 2\vec{r} \cdot \hat{n}) \cdot \hat{n}$

$$4) b) \quad \nabla \times \bar{H} = \bar{J}_{\text{free}} = 0$$

for $z < 0$ the medium is homogeneous so

the μ in $\nabla \times (\mu \bar{B}) = 0$ can be pulled out

~~can~~

$$\mu (\nabla \times \bar{B}) = 0$$

$$\text{but } \nabla \times \bar{B} = \frac{(\bar{J}_{\text{free}} + \bar{J}_{\text{bound}})}{\mu}$$

~~μ~~

\bar{J}_{bound}	= 0
μ	

This argument is not valid in the surface
because there is a change on μ
(in fact a discontinuity)

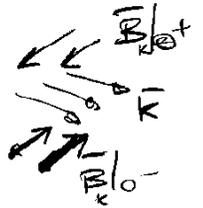
4) c)

$$\vec{B} = \vec{B}_J + \vec{B}_K$$

field of current at $z > 0$
 field created by surface current

$$\vec{B}_{J\parallel}|_{z=0} + \vec{B}_{K\parallel}|_{z=0} = 0 \quad (\text{desired boundary condition})$$

if we are close to the surface the field created by the surface itself is:



$$\vec{B}_K|_{z=0^+} = \frac{1}{2} \vec{K} \times \hat{z} \mu_0 = \vec{B}_{K\parallel}|_{z=0}$$

so $\frac{\mu_0}{2} \vec{K} \times \hat{z} = -\vec{B}_{J\parallel}|_{z=0}$

remember that $\vec{K} = K_{\parallel}$

$$\hat{z} \times (\vec{K} \times \hat{z}) = \frac{-2}{\mu_0} \hat{z} \times \vec{B}_{J\parallel}|_{z=0} = \frac{-2}{\mu_0} \hat{z} \times \vec{B}_J|_{z=0}$$

$$\vec{K} (\hat{z} \cdot \hat{z}) - (\hat{z} \cdot \vec{K}) \hat{z}$$

$$\vec{K} = \frac{-2}{\mu_0} \hat{z} \times \vec{B}_J|_{z=0}$$

Is there a mistake in the problem set?
 I don't see the error.

~~The current~~
 4)d) The ~~current~~ field created by surface current is symmetric respect to $z=0$ (an changed in direction \hat{z})

so for $z < 0$ ^{it is} like the ~~images~~ same images ~~there~~ we used to solve $z > 0$ were in ~~the~~ $z > 0$ and ~~there~~ with the perpendicular component inverted; so they match with ~~the~~ the real currents and duplicate it.

So

$$\vec{B}(x, y, z) = 2 \vec{B}_J(x, y, z) \quad !$$

↑
for $z < 0$

4) e)

$$\bar{F} = \int (\bar{k} \times \bar{B}|_{z=0}^{\text{average}}) ds$$

$$\bar{B}|_{z=0}^{\text{average}} = \left[\underbrace{2\bar{B}_J|_{z=0}}_{\text{below}} + \underbrace{\bar{B}_J|_{z=0} + \bar{B}_K|_{z=0}}_{\text{above}} \right] / 2$$

(see ~~part c~~ part c)

$$= \frac{3\bar{B}_J|_{z=0} - \bar{B}_J|_{z=0}}{2} = \bar{B}_J|_{z=0}$$

so

~~and $\bar{k} = \frac{2}{\mu_0} \hat{z} \times \bar{B}_J|_{z=0}$~~

and $\bar{k} = -\frac{2}{\mu_0} \hat{z} \times \bar{B}_J|_{z=0}$

so

$$\bar{F} = \int -\frac{2}{\mu_0} (\hat{z} \times \bar{B}_J|_{z=0}) \times \bar{B}_J|_{z=0} ds$$

$$\bar{F} = \frac{2}{\mu_0} \int \bar{B}_J|_{z=0} \times (\hat{z} \times \bar{B}_J|_{z=0}) ds$$

$$\bar{F} = \frac{2}{\mu_0} \int (\bar{B}_J|_{z=0})^2 \hat{z} - (\bar{B}_J|_{z=0} \cdot \hat{z}) \bar{B}_J|_{z=0} ds$$

so

$$F_z = \frac{2}{\mu_0} \int (\bar{B}_J|_{z=0})^2 - (\bar{B}_J|_{z=0} \cdot \hat{z})^2 ds$$

~~$F_z = \frac{2}{\mu_0} \int (\bar{B}_J|_{z=0} \cdot \hat{x})^2 + (\bar{B}_J|_{z=0} \cdot \hat{y})^2 ds = |\bar{B}_J|_{z=0}|^2$~~

5) I will do this ex. starting from the previous calculation (since (20); (22); (28) are not independent results)

from (20) $\bar{D} = \epsilon_0 \bar{E} + \bar{P} - \frac{1}{2} \bar{R}$

by definition $\bar{H} = \frac{\bar{B}}{\mu_0} - \bar{M} - \bar{N} + \dots$

microscopic Maxwell equations

in fact (28) is a def. of $\bar{J}_f + \bar{J}_m$ once the def. of \bar{D} is given.

$$\bar{\nabla} \times \frac{\bar{B}}{\mu_0} = \bar{J} + \epsilon_0 \frac{\partial \bar{E}}{\partial t}$$

inverting (20) and the definition of \bar{H}

$$\bar{\nabla} \times \bar{H} + \bar{\nabla} \times \bar{M} + \bar{\nabla} \times \bar{N} = \bar{J} + \frac{\partial \bar{D}}{\partial t} - \frac{\partial \bar{P}}{\partial t} + \frac{1}{2} \frac{\partial \bar{R}}{\partial t}$$

$$\bar{\nabla} \times \bar{H} = \bar{J} - \bar{\nabla} \times \bar{M} - \bar{\nabla} \times \bar{N} - \frac{\partial \bar{P}}{\partial t} + \frac{1}{2} \frac{\partial \bar{R}}{\partial t} + \frac{\partial \bar{D}}{\partial t}$$

this term is $\bar{J}_m + \bar{J}_f$ (both free currents)

so

$$\bar{J} = \langle \bar{J} \rangle = \bar{J}_m + \bar{J}_f + \bar{\nabla} \times \bar{M} + \frac{\partial \bar{P}}{\partial t} - \frac{1}{2} \frac{\partial \bar{R}}{\partial t}$$