

Problem set #2 Solutions

P. 209.

1) a)

$$G(\vec{r}; \vec{r}') = \frac{1}{\sqrt{\underbrace{(x-x')^2 + (y-y')^2}_{D^2} + (z-z')^2}}$$

$$G(x; y; x'; y') = \int_{-Z}^Z G(\vec{r}; \vec{r}') d(z-z')$$

$$= \int_{-Z}^Z \frac{1}{\sqrt{D^2 + \xi^2}} d\xi$$

$$= \ln \left(\xi + \sqrt{D^2 + \xi^2} \right) \Big|_{-Z}^Z$$

$$= \ln \left(\frac{Z + \sqrt{D^2 + Z^2}}{-Z + \sqrt{D^2 + Z^2}} \right)$$

$$\stackrel{\approx}{\uparrow} \ln \left(\frac{Z + Z + D^2/Z}{-Z + Z + D^2/Z} \right) \sim \ln \left(\frac{2Z^2}{D^2} \right)$$

 $D \ll Z$

$$\begin{aligned} G(\vec{r}; \vec{r}') &= -\ln D^2 = -\ln \left[(x-x')^2 + (y-y')^2 \right] \\ &= -\ln \left[\rho^2 + \rho'^2 - 2\rho\rho' \cos(\phi - \phi') \right] \end{aligned}$$

$$1) \text{b)} \quad \nabla^2 G^{2D}(\bar{r}, \bar{r}') = -4\pi \delta(\bar{r} - \bar{r}')$$

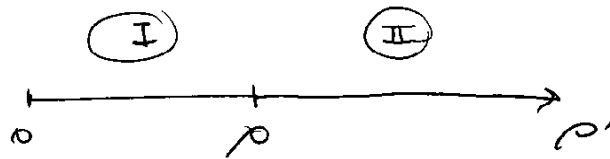
$$\left(\frac{1}{\rho'} \frac{\partial}{\partial \rho'} \rho' \frac{\partial}{\partial \rho'} + \frac{1}{\rho'^2} \frac{\partial^2}{\partial \phi'^2} \right) \frac{1}{2\pi} \sum_m e^{im(\phi - \phi')} g_m(\rho; \rho') = \frac{-4\pi \delta(\rho - \rho') f(\phi - \phi')}{\rho'}$$

$$\begin{aligned} \frac{1}{2\pi} \sum_m \left(\frac{1}{\rho'} \frac{\partial}{\partial \rho'} \rho' \frac{\partial}{\partial \rho'} + \frac{1}{\rho'^2} m^2 \right) g_m(\rho; \rho') e^{im(\phi - \phi')} &= \frac{-4\pi \delta(\rho - \rho')}{\rho'} \underbrace{\sum_m \frac{e^{im(\phi - \phi')}}{2\pi}}_{\delta(\phi - \phi')} \\ &= \sum_m \frac{-4\pi \delta(\rho - \rho')}{\rho'} \frac{e^{im(\phi - \phi')}}{2\pi} \end{aligned}$$

↓ (uniqueness of
Fourier series)

$$\boxed{\left[\frac{1}{\rho'} \frac{\partial}{\partial \rho'} \rho' \frac{\partial}{\partial \rho'} + \frac{1}{\rho'^2} m^2 \right] g_m(\rho; \rho') = -4\pi \frac{\delta(\rho - \rho')}{\rho'}}$$

1) c)



for regions I & II

$$\left(\frac{1}{\rho'} \frac{\partial}{\partial \rho'} \rho' \frac{\partial}{\partial \rho'} - \frac{m^2}{\rho'^2} \right) g_m^{I/II}(\rho; \rho') = 0$$

↓

$$\begin{cases} g_m^I = A \rho'^{|m|} + B \rho'^{-|m|} \\ g_m^{II} = C \rho'^{|m|} + D \rho'^{-|m|} \end{cases}$$

well behaved at 0 and ∞

g must be continuous at $\rho' = \rho^*$

$$A \rho^{*|m|} = D \rho^{*-|m|}$$

$$\frac{A}{D} = \rho^{*-2|m|}$$

and integrating the original equation

$$\frac{\partial}{\partial \rho'} g \Big|_{\rho+\epsilon}^{\rho+\epsilon} = \frac{-4\pi}{\rho}$$

$$D(-|m|) \rho^{-|m|-1} - A|m| \rho^{|m|-1} = -4\pi/\rho$$

$$-|m| D \rho^{-|m|} = \frac{-4\pi + A|m|\rho^{|m|}}{|m|}$$

$$-D = -\frac{4\pi}{|m|} \rho^{|m|} + A \rho^{2m}$$

$$-D = -\frac{4\pi}{|m|} \rho^{|m|} + D \cancel{\rho^{-2|m|}} \rho^{2|m|}$$

$$-2D = -\frac{4\pi}{|m|} \rho^{|m|}$$

$$D = \frac{2\pi}{|m|} \rho^{|m|}$$

$$A = \frac{2\pi}{|m|} \rho^{-|m|}$$

final solution

$$\textcircled{\text{I}} \quad g_m(\rho' < \rho) = \frac{2\pi}{|m|} \rho^{-|m|} \rho'^{|m|} = \frac{2\pi}{|m|} \left(\frac{\rho'}{\rho}\right)^{|m|}$$

$$\textcircled{\text{II}} \quad g_m(\rho' > \rho) = \frac{2\pi}{|m|} \rho^{|m|} \rho'^{-|m|} = \frac{2\pi}{|m|} \left(\frac{\rho}{\rho'}\right)^{|m|}$$

$$\boxed{g_m(\rho, \rho') = \frac{2\pi}{|m|} \left(\frac{\rho_{<}}{\rho_{>}}\right)^{|m|} \xrightarrow{\text{in the limit } m \rightarrow 0} g_0 = 2\pi \ln(\rho_{>}^2) + \text{inessential constant}}$$

$$\boxed{G(\rho; \rho'; \phi; \phi') = -\ln(\rho_{>}^2) + 2 \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho_{<}}{\rho_{>}}\right)^m \cos[m(\phi - \phi')]$$

2) a)

$$\begin{matrix} q \\ \bullet \\ -2q \\ q \end{matrix}$$

$$\begin{aligned} \Phi(x,y,z) &= \frac{q}{\sqrt{x^2 + y^2 + (z-a)^2}} - \frac{2q}{\sqrt{x^2 + y^2 + z^2}} + \frac{q}{\sqrt{x^2 + y^2 + (z+a)^2}} \\ &= \frac{q}{\sqrt{r^2 + a^2 - 2ar \cos \theta}} - \frac{2q}{r} + \frac{q}{\sqrt{r^2 + a^2 + 2ar \cos \theta}} \end{aligned}$$

~~$\frac{1}{\sqrt{r^2 + a^2 - 2ar \cos \theta}} \sim \frac{1}{\sqrt{r^2 - 2ar \cos \theta}}$~~
 ~~$[r^2 - 2ar \cos \theta]^{-1/2}$~~
 ~~$+ \frac{1}{2} [r^2 - 2ar \cos \theta]^{-3/2} (2ar \cos \theta)$~~

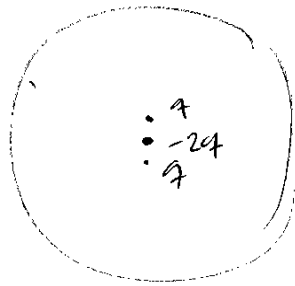
Taylor series in a

$$\begin{aligned} & [r^2 + a^2 \mp 2ar \cos \theta]^{-1/2} \\ & \downarrow \\ & -\frac{1}{2} [r^2 + a^2 \mp 2ar \cos \theta]^{-3/2} (2a \mp 2r \cos \theta) \\ & \downarrow \\ & \left(-\frac{1}{2} \right) \left(-\frac{3}{2} \right) [r^2 + a^2 \mp 2ar \cos \theta]^{-5/2} (2a \mp 2r \cos \theta)^2 + \left(-\frac{1}{2} \right) [r^2 + a^2 \mp 2ar \cos \theta]^{-3/2} (2) \\ & \downarrow \\ & [r^2 + a^2 \mp 2ar \cos \theta]^{-1/2} \sim r^{-1} \pm r^{-3} 2r \cos \theta + \left[\left(\frac{3}{4} \right) r^{-5} 4 r^2 \cos^2 \theta - r^{-3} \right] \frac{a^2}{2} \end{aligned}$$

$$\phi(x,y,z) = q \left(r^{-1} + r^{-3} 2a \cos \theta + r^{-3} (3 \cos^2 \theta - 1) \frac{a^2}{2} \right) - 2q r^{-1} + q \left(r^{-1} - r^{-3} 2a \cos \theta + r^{-3} (3 \cos^2 \theta - 1) \frac{a^2}{2} \right) =$$

$$\boxed{\Phi = \frac{2q}{r^3} \left(\frac{3 \cos^2 \theta - 1}{2} \right)} \leftarrow \text{4-pole field.}$$

2.8) b) Turn-on sphere
- 4'



• 4'

2 images + "image" of $-2q$ at infinite = overall increase of potential.

$$\Phi_{\text{images}} = -q \left[\frac{b/a}{\left(r^2 + \frac{b^2}{a^2} - \frac{2rb^2}{a} \cos\theta\right)^{1/2}} + \frac{2/a}{\left(r^2 + \frac{b^2}{a^2} - \frac{2rb^2}{a} \cos\theta\right)^{1/2}} - \frac{2}{b} \right]$$

using the same limit as in ↓

$$= +q \frac{1}{b} \frac{a^2 r^2}{b^4} (1 - 3\cos^2\theta)$$

this potential must be added to the previous one:

$$\boxed{\Phi_{\text{FINAL}} = 2Q \left(1 - \frac{rs}{b^5}\right) P_2(\cos\theta)}$$

↑
gaussian
units.

~~3a)~~ 3a)

In the convention where all $Q^{(e)}$ can be written as

$$Q_{x_i x_j \dots}^{(e)} = \int \underbrace{x_i x_j \dots}_e \rho(\bar{x}) d^3r \quad i, j, k, \dots = 1, 2 \text{ or } 3$$

l elements

translating the origin:

$$\begin{aligned} \tilde{Q}_{x_i x_j \dots}^{(e)} &= \int x_i x_j \dots \rho(\bar{x} + \tilde{x}) d^3r \\ &= \int (x_i - \tilde{x}_i)(x_j - \tilde{x}_j)(x_k - \tilde{x}_k) \dots \rho(\bar{x}) d^3r \end{aligned}$$

expanding this product

$$= \int x_i x_j x_k \dots \rho(\bar{x}) d^3r + \leftarrow Q_{x_i x_j \dots}^{(e)}$$

$$+ (-\tilde{x}_i) \int (x_j x_k \dots) \rho(\bar{x}) d^3r$$

$$+ (-\tilde{x}_j) \int (x_i x_k \dots) \rho(\bar{x}) d^3r$$

⋮

$$+ (\tilde{x}_i \tilde{x}_j \tilde{x}_k \dots) \int \rho(\bar{x}) d^3r$$

combinations of $Q^{(e')}$ where $e' < e$ all equal to 0

so

$$= Q_{x_i x_j \dots}^{(e)}$$

Q.E.D.

~~3a)~~

3b)

$$P_i = \int x_i \rho(\vec{r})$$

$$\tilde{P}_i = \int (x_i - \tilde{x}_i) \rho(\vec{r}) = \int x_i \rho(\vec{r}) - \tilde{x}_i \int \rho(\vec{r})$$

$$= P_i - \tilde{x}_i Q$$

$$\tilde{\vec{p}} = \vec{p} - \tilde{\vec{R}} Q$$

$$Q_{ij} = \int (3 x_i x_j - r^2 \delta_{ij}) \rho(\vec{r}) d^3x$$

$$\tilde{Q}_{ij} = \int \left[3 (x_i - \tilde{x}_i) (x_j - \tilde{x}_j) - (r^2 - 2\vec{r} \cdot \tilde{\vec{R}} - \tilde{R}^2) \delta_{ij} \right] \rho(\vec{r}) d^3r$$

$$= \int (3 x_i x_j - 3 x_i \tilde{x}_j - 3 \tilde{x}_i x_j - 3 \tilde{x}_i \tilde{x}_j - r^2 \delta_{ij} + 2\vec{r} \cdot \tilde{\vec{R}} \delta_{ij} + \tilde{R}^2 \delta_{ij}) \rho(\vec{r}) d^3r$$

$$= \int (3 x_i x_j - r^2 \delta_{ij}) \rho(\vec{r}) - 3 \tilde{x}_j \int x_i \rho(\vec{r}) - 3 \tilde{x}_i \int x_j \rho(\vec{r}) - 3 \tilde{x}_i \tilde{x}_j \int \rho(\vec{r}) d^3r + 2 \tilde{\vec{R}} \cdot \int \vec{r} \rho(\vec{r}) \delta_{ij} + \tilde{R}^2 \delta_{ij} \int \rho(\vec{r})$$

$$\tilde{Q}_{ij} = Q_{ij} - 3 \tilde{x}_j P_i - 3 \tilde{x}_i P_j - 3 \tilde{x}_i \tilde{x}_j Q + 2 \tilde{\vec{R}} \cdot \vec{p} \delta_{ij} + \tilde{R}^2 Q \delta_{ij}$$

$$\tilde{Q} = Q - 3 \vec{p} \otimes \tilde{\vec{R}} - 3 \tilde{\vec{R}} \otimes \vec{p} - 3 R \otimes R Q + 2 \tilde{\vec{R}} \cdot \vec{p} \mathbb{1} + \tilde{R}^2 Q \mathbb{1}$$

3)c) consider $\tilde{\vec{R}} = \frac{\vec{p}}{Q}$

for a general Q_{ij} there are 5 parameter
 an \vec{R} only gives 3 parameters to play with
 so the system is over-constrained & in general
 has no sol.

$$4) a) \quad W = \int \rho \Phi \quad \Phi = \Phi_0 + \partial_i \phi x_i + \frac{1}{2} \partial_i \partial_j \phi x_i x_j$$

$$W = \int \rho \Phi_0 + \int \rho \partial_i \phi x_i + \frac{1}{2} \int \rho \partial_i \partial_j \phi x_i x_j$$

$$= \Phi_0 \int \rho + \partial_i \phi \int \rho x_i + \frac{1}{2} \partial_i \partial_j \phi \int \rho x_i x_j + \dots$$

$$W(\vec{x}) = \phi(\vec{x}) q + \partial_i \phi(\vec{x}) p_i + \frac{1}{6} \partial_i \partial_j \phi \int \rho (x_i x_j - \delta_{ij} r^2)$$

$$+ \frac{\partial_i \partial_j \phi}{\epsilon_0} \int \rho r^2$$

$$\frac{\partial_i \partial_j \phi}{\epsilon_0} = 0$$

⊛

$$W(\vec{x}) = \phi(\vec{x}) q + \partial_i \phi(\vec{x}) p_i + \frac{1}{6} \partial_i \partial_j \phi Q_{ij} + \dots$$

$$W(\vec{x}) = q\phi(\vec{x}) - \vec{E} \cdot \vec{p} - \frac{1}{6} \partial_i E_j Q_{ij} + \dots$$

$$\vec{F} = -\vec{\nabla} W$$

$$\vec{F} = -\vec{\nabla} \phi(\vec{x}) q + \vec{\nabla} (\vec{E} \cdot \vec{p}) + \frac{1}{6} \vec{\nabla} [\partial_i E_j Q_{ij}]$$

$$\vec{E} q$$

⊗ is still valid but now rotations can change the momenta (for example rotating the dipole moment)

$$q \rightarrow q \quad (\text{scalar})$$

$$\vec{p} \rightarrow \vec{p} + \hat{x}_i \times \vec{p} \delta\theta$$

$$p_i \rightarrow p_i + \frac{\epsilon_{ijk} p_k \delta\theta}{\delta p_i}$$

$$Q_{ij} \rightarrow Q_{ij} + (\epsilon_{ikl} Q_{kj} + \epsilon_{jlk} Q_{ki}) \delta\theta$$

$$\frac{\delta W_1}{\delta\theta} = \left\{ \partial_i \phi \epsilon_{ijk} p_k + \frac{1}{6} \partial_i \partial_j \phi \left(\underbrace{\epsilon_{ikl} Q_{kj}}_{Q_{2j} \delta_{i3} - Q_{3j} \delta_{i2}} + \underbrace{\epsilon_{jlk} Q_{ki}}_{Q_{2i} \delta_{j3} - Q_{3i} \delta_{j2}} \right) \right\} \delta\theta$$

- N₁

$$N_1 = - [\vec{p} \times \vec{\nabla} \phi]_1 - \frac{1}{6} \left\{ \partial_i \partial_j \phi Q_{2j} \delta_{i3} - \partial_i \partial_j \phi Q_{3j} \delta_{i2} + \partial_i \partial_j \phi Q_{2i} \delta_{j3} - \partial_i \partial_j \phi Q_{3i} \delta_{j2} \right\}$$

same

$$= - [\vec{p} \times \vec{\nabla} \phi]_1 - \frac{1}{6} \left\{ \partial_3 \partial_j \phi Q_{2j} - \partial_2 \partial_j \phi Q_{3j} + \partial_i \partial_3 \phi Q_{2i} - \partial_i \partial_2 \phi Q_{3i} \right\}$$

same.

$$N_1 = [\vec{p} \times \vec{E}] + \frac{1}{3} \left\{ \partial_3 E_j Q_{2j} - \partial_2 E_j Q_{3j} \right\}$$

This is an elegant way \rightarrow starting with $\vec{N} = \int \rho \vec{r} \times \vec{E}(r)$ is also correct.

5) From 4)

5)

$$W = -\frac{1}{6} (\partial_i E_j Q_{ij}) \rightarrow$$

$$\bar{Q} = \begin{pmatrix} eQ & 0 & 0 \\ 0 & -eQ/2 & 0 \\ 0 & 0 & eQ \end{pmatrix}$$

"is like"

by symmetry

$$\partial_x E_y = -\partial_y E_x$$

$$\text{and } \partial_x E_z = 0$$

$$\partial_y E_x = 0$$

$$\text{and } \partial_z E_x = 0$$

$$\partial_z E_y = 0$$

so off-diagonal elements cancel each other.

$$W = -\frac{1}{6} \left[\partial_x E_x \frac{eQ}{2} - \partial_y E_y \frac{eQ}{2} + \partial_z E_z eQ \right]$$

(Jackson is not very clear)

$$= -\frac{e}{6} \left[-(\partial_x E_x + \partial_y E_y) \frac{Q}{2} + \partial_z E_z Q \right]$$

$$\left. \begin{aligned} \bar{E} \text{ is axially symmetrical} &\Rightarrow \partial_x E_x = \partial_y E_y \\ \nabla \cdot \bar{E} = e &\Rightarrow \partial_x E_x + \partial_y E_y + \partial_z E_z = e \end{aligned} \right\}$$

$$\Downarrow$$

$$\partial_x E_x = \partial_y E_y = -\frac{\partial_z E_z}{2}$$

$$= -\frac{e}{6} \left[-(-\partial_z E_z) \frac{Q}{2} + (\partial_z E_z) Q \right]$$

$$= -\frac{e}{6} \frac{3}{2} (\partial_z E_z) Q$$

$$W = -\frac{e}{4} Q (\partial_z E_z)$$

5) b)

$$Q = 2 \times 10^{-28} \text{ m}^2$$

$$W/h = 10 \text{ MHz}$$

$$W = -\frac{e}{4} \Delta \left(\frac{\partial \epsilon}{\partial z} \right)_0$$

$$\left(\frac{\partial \epsilon}{\partial z} \right)_0 = \frac{-4W}{eQ} = \boxed{-0.08 \left(\frac{e}{4\pi \epsilon_0 a_0^3} \right)}$$

5) c)

$$eQ = Q_{33} = \int (3z^2 - r^2) \rho(r) d^3x$$

$$= \rho \int_0^{2\pi} d\phi \int_{z=-b}^b dz \int_0^{\frac{a}{b} \sqrt{b^2 - z^2}} (3z^2 - r^2) r dr$$

$$= \rho 2\pi \int_{-b}^b dz \left[\frac{3z^2 r^2}{2} - \frac{1}{4} r^4 \right]_0^{\frac{a}{b} \sqrt{b^2 - z^2}}$$

$$= \rho 2\pi \int_{-b}^b dz \left\{ \frac{3z^2 a^2}{b^2} (b^2 - z^2) - \frac{1}{4} \frac{a^4}{b^4} (b^2 - z^2)^2 \right\}$$

$$= \rho 2\pi \int_{-b}^b dz \left[\frac{3z^2 a^2}{b^2} b^2 - \frac{3z^4 a^2}{b^2} - \frac{1}{4} \frac{a^4}{b^4} b^4 + \frac{a^4}{4b^4} 2z^2 b^2 - \frac{1}{4} \frac{a^4}{b^4} z^4 \right]$$

$$eQ = \rho 2\pi \frac{4}{15} a^2 b (b^2 - a^2) \leftarrow \left(\rho = \frac{Ze}{\frac{4}{3}\pi a^2 b} \right)$$

$$Q = \frac{2}{5} Z(a+b)(a-b) \Rightarrow \left| \frac{a-b}{a} \approx 0.1 \right|$$

